### **Chapter 4- Buoyancy and Stability**

**Buoyancy:** resultant force exerted on a body by static fluid which is submerged or floating. It always acts vertically upward.



- The buoyancy force acts through the centroid of the displaced liquid volume.
- It can be proven that the Buoyancy force equals the weight of the displaced liquid.
- For equilibrium,  $F_{\rm B} = W$ ,  $F_{\rm B} = \gamma V_{\rm displaced liquid}$

*Example:* A 0.2 m cube is floating as shown, find the density of the cube material.



**Hydrometer:** an instrument used to measure the specific gravity of liquids. It consists of bulb and constant area stem. When placed in pure water the specific gravity is marked to read 1.0. The force balance is

## $W = \gamma_{water} V_{displaced}$

Where W is the weight of the hydrometer and V is the submerged volume below the S=1.0 line. In an unknown liquid of specific gravity,  $\gamma_x$ , a force balance would be:

$$W = \gamma_x (V - A \Delta h)$$

Where A is the cross-sectional area of the stem. Equating the two equations above gives

$$\Delta h = \frac{V}{A} \left( 1 - \frac{1}{S_x} \right)$$

Where Sx = $\gamma_x / \gamma_{water}$ 



Hydrometer: (a) in water, (b) in unknown liquid

#### Stability

Stability becomes an important consideration when floating bodies such as a boat or ferry is designed. It is an obvious requirement that a floating body such as a boat does not topple when slightly disturbed. We say that a body is in stable equilibrium if it is able to return to its position when slightly disturbed. Failure to do so denotes unstable equilibrium

#### **Stability of submerged bodies**



Stability of floating bodies: in this case, the stability is more complicated to deal with.

When the body is slightly rotated about O,

- 1- The center of gravity remains unchanged.
- 2- The center of buoyancy is changed to C'

The center of the buoyancy (C, the centroid of the displaced volume of fluid) of a floating body depends on the shape of the body and on the position in which it is floating.



I<sub>o</sub>: second moment area of the

waterline area about an axis passing through the Origin O.

V<sub>displac</sub>: Volume of displaced liquid or (submerged body)

Chapter 4

<u>Example</u>: A 0.25 long cylinder with 0.25 m diameter composed of material with density of  $\rho = 815 \text{ kg/m}^3$ . Will it float on water on its base?



### **Chapter-5 Accelerated Fluid**

When a fluid mass is moving with constant acceleration, we assume no relative motion between the fluid layers, i.e. no shear stress.

## 1- Linear motion with constant acceleration.

Assume a fluid in a vessel (of unit width), the vessel is moving with constant acceleration.



Equation of Newton 2<sup>nd</sup> law in x-direction

$$ma_{x} = \sum F_{x}$$

$$d_{m}a_{x} = Pd_{y} - \left(P + \frac{\partial P}{\partial x}dx\right)dy$$

$$d_{m}a_{x} = -\frac{\partial P}{\partial x}dxdy$$

$$\therefore a_{x} = -\frac{1}{\rho}\frac{\partial P}{\partial x}$$
(1)

Equation of Newton 2<sup>nd</sup> law in y-direction

$$ma_{y} = \sum F_{y}$$

$$d_{m}a_{y} = Pd_{x} - \left(P + \frac{\partial P}{\partial y}dy\right)dx - gdm$$

$$d_{m}a_{y} = -\frac{\partial P}{\partial y}dxdy - gdm$$

$$dm = \rho(dx * dy * 1)$$

$$\therefore a_{y} = -g - \frac{1}{\rho}\frac{\partial P}{\partial y}$$
(2)

Note: if  $a_y = 0$ , the pressure along y direction will vary hydrostatically i.e.  $P = \gamma h$ .

But, 
$$dP = \frac{\partial P}{\partial x}dx + \frac{\partial P}{\partial y}dy$$

Hence, from equations (1) and (2),

$$dP = -\rho a_x d_x - \left(\rho g + \rho a_y\right) dy \tag{3}$$

The line of constant pressure, can be found from the above equation, by setting dP = 0

$$\Rightarrow \rho a_x d_x = -\rho (g + a_y) dy$$

$$\therefore \frac{dy}{dx} = -\frac{a_x}{g + a_y} \quad \text{(negative slope).}$$

The line of constant pressure is free surface itself.

#### 2- Rotation with constant acceleration

#### **Assumptions:**

- No pressure variation with  $\theta$  direction
- The horizontal rotation will not alter the pressure distribution in the vertical direction (i.e. the pressure equals to  $P = \gamma h$ ).

Applying Newton's 2<sup>nd</sup> low in r-direction:

 $-ma_r = \sum F_r$ 



 $-dm a_r = \sum F_r$  $-\rho r d\theta dr dz a_r = Pr d\theta dz - \left(P + \frac{\partial P}{\partial r} dr\right) dz r d\theta$ 

$$\therefore \frac{\partial P}{\partial r} = \rho a_r$$
$$a_r = r\omega^2$$
$$\therefore \frac{\partial P}{\partial r} = \rho r\omega^2$$
(1)

$$-ma_{z} = \sum F_{z} = 0, \quad a_{z} = 0$$

$$P \ rd\theta \ dr - \left(P + \frac{\partial P}{\partial z} dz\right) r \ dr \ d\theta - \rho \ r \ dr \ d\theta \ dz \ g = 0$$

$$\therefore \frac{\partial P}{\partial z} = -\rho \ g \tag{2}$$
But, 
$$dP = \frac{\partial P}{\partial r} dr + \frac{\partial P}{\partial z} dz$$

# $dP = \rho \, r \, \omega^2 dr - \rho g \, dz \tag{3}$

on the free surface, dP = 0.

$$\omega^2 \left( \frac{r_2^2}{2} - \frac{r_1^2}{2} \right) = g(z_2 - z_1)$$

If we put point 1 at the z-axis so that  $r_1 = 0$ 

$$\omega^2 \frac{r_2^2}{2} = g(z_2 - z_1)$$
 Equation of Parabola.

#### Example 5.1

The tank shown in Fig. 1a is accelerated to the right. Calculate the acceleration ax needed to cause the free surface shown in Fig. 1b to touch point A. Calculate also the pressure at point B.



### Example 5.2

•

A closed box with horizontal base of 6x6 m and height of 2 m is half filled with water. It is given  $a_x = g/2$  and  $a_y = -g/4$ . Find the pressure at point b as shown.



### Example 5.3

A water-filled cylinder is rotating about its center line. Calculate the rotational speed that is necessary for the water to just touch the origin and the pressures at A and B.

