

## MOMENTS OF INERTIA

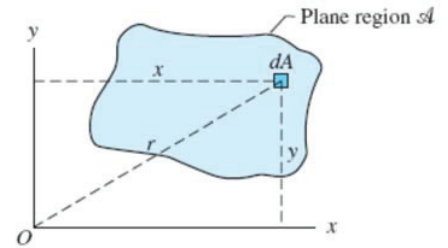
### 5.1 Moment of Inertia of Area

The *moments of inertia of the area* about the  $x$ - and  $y$ -axes, respectively, are defined by

$$I_x = \int_A y^2 dA \quad I_y = \int_A x^2 dA \quad \dots(5-1)$$

Because the distances  $x$  and  $y$  are squared,  $I_x$  and  $I_y$  are sometimes called the *second moments of the area*.

The dimension for moment of inertia of area is  $[L^4]$ . Therefore, the units are  $\text{in}^4$ ,  $\text{mm}^4$ , and so for the other units. Although the first moment of an area can be positive, negative, or zero, its moment of inertia is always positive, because both  $x$  and  $y$  in Eqs. (5.1) are squared.



### 5.2 Polar Moment of Inertia

The polar moment of inertia of the area about point  $O$  (strictly speaking, about an axis through  $O$ , perpendicular to the plane of the area) is defined by:

$$J_o = \int_A r^2 dA \quad \dots(5-1)$$

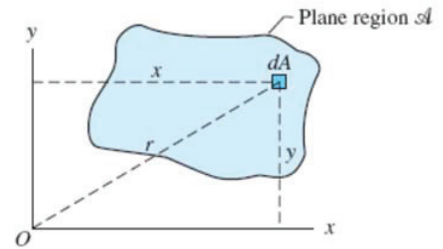
where  $r$  : is the distance from  $O$  to the differential area element  $dA$ .

Note that the polar moment of an area is always positive and its dimension is  $[L^4]$

From Figure, we note that  $r^2 = y^2 + x^2$ , which gives the following relationship between polar moment of inertia and moment of inertia:

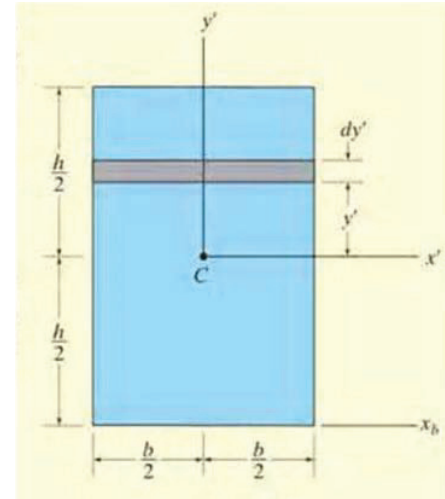
$$J_o = \int_A r^2 dA = \int_A (x^2 + y^2) dA = \int_A x^2 dA + \int_A y^2 dA$$

$$\therefore J_o = I_x + I_y \quad \dots(5-2)$$



**Example 2:** Determine the moment of inertia for the rectangular area shown in Figure (a) with respect to

- the centroidal  $x'$ -axis,
- the  $x_b$  passing through the base of the rectangle, and
- the pole or  $z'$ -axis perpendicular to the  $x'$ - $y'$  plane and passing through the centroid  $C$ .



**Solution: Part (a).** The horizontal differential element is chosen for integration. Here it is necessary to integrate from  $y' = -h/2$  to  $y' = h/2$  since  $dA = bdy'$ , then

$$\begin{aligned}\bar{I}_{x'} &= \int_A y'^2 \cdot dA = \int_{-h/2}^{h/2} y'^2 (bdy') = b \left[ \frac{y'^3}{3} \right]_{-h/2}^{h/2} \\ &= \frac{b}{3} \left[ \left( \frac{h}{2} \right)^3 - \left( -\frac{h}{2} \right)^3 \right] = \frac{b}{3} \left[ \frac{h^3}{8} + \frac{h^3}{8} \right] = \frac{2bh^3}{(3)(8)} = \frac{bh^3}{12}\end{aligned}$$

**Part (b):** Applying the parallel-axis theorem.

$$\begin{aligned}I_{x_b} &= \bar{I}_{x'} + Ad_y^2 \\ &= \frac{bh^3}{12} + bh \left( \frac{h}{2} \right)^2 = \frac{bh^3}{3}\end{aligned}$$

**Part (c):** To obtain the polar moment of inertia about point  $C$ , we must first obtain  $\bar{I}_{y'}$ , which may be found by interchanging the dimensions  $b$  and  $h$  in the result of part (a), i.e.,

$$\bar{I}_{y'} = \frac{hb^3}{12}$$

So the polar moment of inertia about  $C$  is therefore

$$\bar{J}_C = \bar{I}_{x'} + \bar{I}_{y'} = \frac{bh}{12} (h^2 + b^2)$$

This relationship states that the polar moment of inertia of an area about a point  $O$  equals the sum of the moments of inertia of the area about two perpendicular axes that intersect at  $O$ .

### 5.3 Parallel-Axis Theorems:

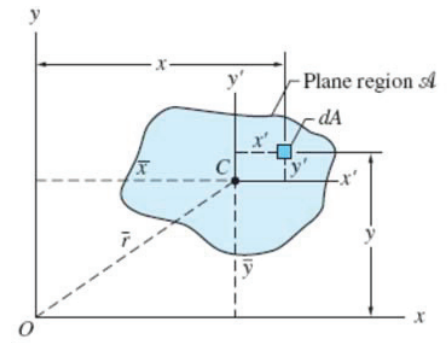
Observe that the  $y$ -coordinate of the differential area  $dA$  can be written as  $y = \bar{y} + y'$  where  $\bar{y}$  (the centroidal coordinate of the area) is the distance between the two axes.

$$I_x = \int_A y^2 dA = \int_A (\bar{y} + y')^2 dA = \bar{y}^2 \int_A dA + 2\bar{y} \int_A y' dA + \int_A (y')^2 dA$$

Where  $\int_A dA = A$  the area of the region,

$\int_A y' dA = 0$  the first moment of the area about a centroidal axis vanishes,

$\int_A (y')^2 dA = \bar{I}_x$  the second moment of the area about the  $x'$ -axis).



(a)

Above equation simplifies to

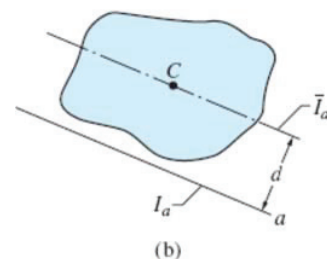
$$I_x = \bar{I}_x + A\bar{y}^2 \quad \dots(5-3a)$$

This relationship is known as the **parallel-axis theorem** for moment of inertia of an area. The distance  $\bar{y}$  is sometimes called the **transfer distance** (the distance through which the moment of inertia is to be “transferred”).

**Note:** It is important to remember that the theorem is valid only if  $\bar{I}_x$  is the moment of inertia about the centroidal  $x$ -axis. If this is not the case, the term  $\int_A y' dA$  in Eq. (a) would not vanish, giving rise to an additional term in Eq. (5-3a).

In general, the parallel-axis theorem can be written as:

$$I_a = \bar{I}_a + Ad^2 \quad \dots(5-3b)$$



(b)

**Example 3:** Determine the moment of inertia for the shaded area shown in Figure (a) about the  $x$ -axis:

**Solution I:** A differential element of the area that is parallel to the  $x$ -axis is chosen for integration. Its area is

$$dA = (100 - x)dy$$

Integrating with respect to  $y$ , from  $y = 0$  to  $y = 200$  mm, yields

$$\begin{aligned} I_x &= \int_A y^2 \cdot dA = \int_0^{200} y^2 (100 - x) \cdot dy = \int_0^{200} y^2 \left( 100 - \frac{y^2}{400} \right) \cdot dy \\ &= \int_0^{200} \left( 100y^2 - \frac{y^4}{400} \right) \cdot dy = \left[ \frac{100y^3}{3} - \frac{y^5}{(400)(5)} \right]_0^{200} \\ &= \left[ \left( \frac{100(200)^3}{3} - \frac{(200)^5}{2000} \right) - \left( \frac{100(0)^3}{3} - \frac{(0)^5}{2000} \right) \right] \\ &= 107 \times 10^6 \text{ mm}^4 \end{aligned}$$

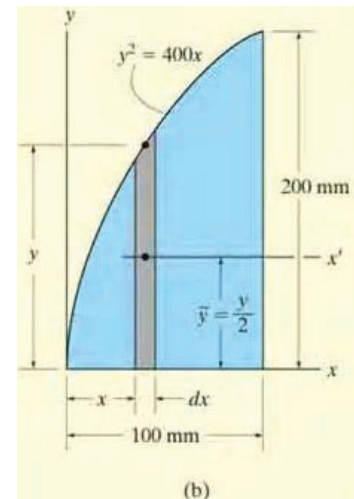
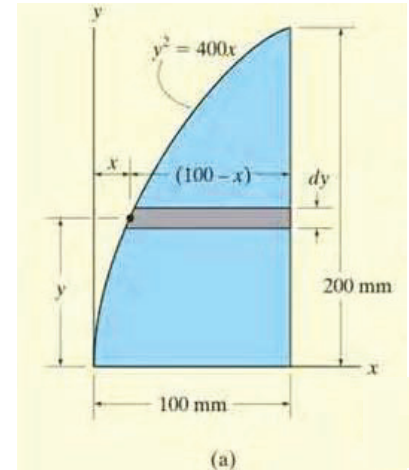
**Solution II:** A differential element parallel to the  $y$ -axis as shown in Figure (b), is chosen for integration. For a differential element chosen in Figure (b),

$$b = dx \quad \text{and} \quad h = y,$$

and thus 
$$d\bar{I}_{x'} = \frac{(dx)(y)^3}{12}.$$

Since the centroid of the element  $\bar{y} = y/2$  from the  $x$ -axis, the moment of inertia of the element about this axis is

$$dI_x = d\bar{I}_{x'} + dA\bar{y}^2 = \frac{y^3}{12} \cdot dx + (y \cdot dx) \left( \frac{y}{2} \right)^2$$



$$= \left( \frac{y^3}{12} + \frac{y^3}{4} \right) dx = \left( \frac{1+3}{12} \right) y^3 \cdot dx = \frac{1}{3} y^3 \cdot dx \quad (\text{This result can also concluded from part (b) of Example 2})$$

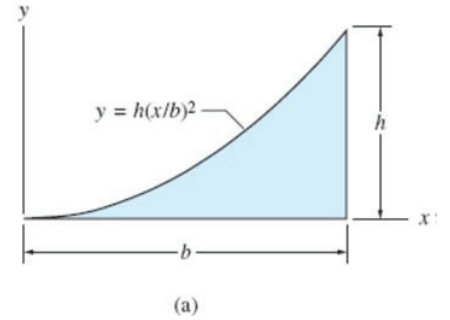
Integrating with respect to  $x$ , from  $x = 0$  to  $x = 100$  mm, yields

$$\begin{aligned} I_x &= \int_A dI_x = \int_0^{100} \frac{1}{3} y^3 \cdot dx = \frac{1}{3} \int_0^{100} (400x)^{3/2} \cdot dx \\ &= \frac{1}{(3)(400)} \left[ \frac{(400x)^{5/2}}{5/2} \right]_0^{100} = \frac{1}{3000} \left[ (400(100))^{5/2} - (400(0))^{5/2} \right] \\ &= 107 \times 10^6 \text{ mm} \end{aligned}$$

**Example 4:** By integration, calculate the moment of inertia about the  $y$ -axis of the area shown in Fig. (a) by the following methods:

- (1) using a vertical differential area element; and
- (2) using a horizontal differential area element.

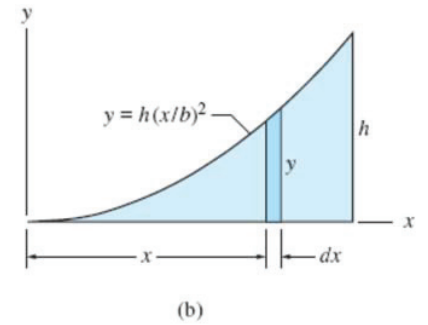
**Solution: Part (1):** The vertical differential area element is shown in Fig. (b).



$$dA = y \, dx = h(x/b)^2 \, dx,$$

we have

$$\begin{aligned} I_y &= \int_A x^2 dA = \int_0^b x^2 \cdot [h(x/b)^2 \, dx] = \frac{h}{b^2} \int_0^b x^4 \cdot dx \\ &= \frac{h}{b^2} \left[ \frac{x^5}{5} \right]_0^b = \frac{h}{b^2} \left[ \frac{b^5}{5} - \frac{(0)^5}{5} \right] = \frac{b^3 h}{5} \end{aligned}$$

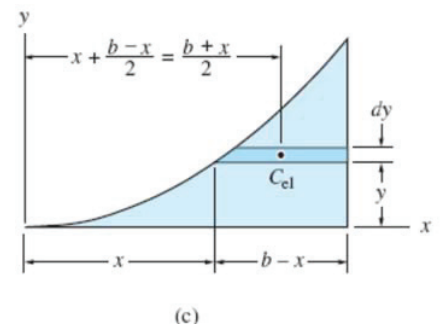


**Part 2:** The horizontal differential area element is shown in Fig. (c).

$$d\bar{I}_y = \frac{dy(b-x)^3}{12}.$$

According to the parallel-axis theorem,

$$dI_y = d\bar{I}_y + dA(d_x^2),$$



where  $d_x$  is the distance between the  $y$ -axis and the vertical centroidal axis of the element. Using  $d_x = \frac{(b+x)}{2}$  as shown in Fig. (c), and integrating, we obtain  $I_y$  for the entire area:

$$I_y = \int_A dI_y = \int_0^h \left[ \frac{dy(b-x)^3}{12} + [(b-x)dy] \left( \frac{b+x}{2} \right)^2 \right] dy$$

Substituting  $x = b(y/h)^{1/2}$  and completing the integration gives

$$\begin{aligned} I_y &= \int_0^h \left[ \frac{(b - b\sqrt{(y/h)})^3}{12} + (b - b\sqrt{(y/h)}) \left( \frac{b + b\sqrt{(y/h)}}{2} \right)^2 \right] dy \\ &= b^3 \int_0^h \left[ \frac{(1 - \sqrt{(y/h)})^3}{12} + (1 - \sqrt{(y/h)}) \left( \frac{1 + \sqrt{(y/h)}}{2} \right)^2 \right] dy \end{aligned}$$

$$\text{Let } z^2 = \frac{y}{h} \quad 2z \cdot dz = \frac{dy}{h} \quad \text{or} \quad dy = 2hz \cdot dz$$

$$\text{Note that when } y = 0 \quad z = 0$$

$$\text{And when } y = h \quad z = 1$$

$$\begin{aligned} &= b^3 \int_0^1 \left[ \frac{(1-z)^3}{12} + (1-z) \left( \frac{1+z}{2} \right)^2 \right] \cdot 2hz \cdot dz \\ &= 2b^3 h \int_0^1 \left[ \frac{1}{12} (1-z)(1-2z+z^2) + \frac{1}{4} (1-z)(1+2z+z^2) \right] z \cdot dz \\ &= 2b^3 h \int_0^1 \left[ \frac{1}{12} (1-2z+z^2-z+2z^2-z^3) + \frac{1}{4} (1+2z+z^2-z-2z^2-z^3) \right] z \cdot dz \\ &= 2b^3 h \int_0^1 \left[ \frac{1}{12} (1-3z+3z^2-z^3) + \frac{1}{4} (1+z-z^2-z^3) \right] z \cdot dz \\ &= \frac{2b^3 h}{12} \int_0^1 [1-3z+3z^2-z^3+3+3z-3z^2-3z^3] z \cdot dz \\ &= \frac{b^3 h}{6} \int_0^1 [4-4z^3] z \cdot dz \\ &= \frac{4b^3 h}{6} \int_0^1 [z-z^4] dz \\ &= \frac{2b^3 h}{3} \left[ \frac{z^2}{2} - \frac{z^5}{5} \right]_0^1 = \frac{2b^3 h}{3} \left[ \left( \frac{(1)^2}{2} - \frac{(1)^5}{5} \right) - \left( \frac{(0)^2}{2} - \frac{(0)^5}{5} \right) \right] \end{aligned}$$

$$= \frac{2b^3h}{3} \left( \frac{5-2}{10} \right) = \frac{2b^3h}{3} \left( \frac{3}{10} \right) = \frac{b^3h}{5}$$

**Note:** Obviously, the horizontal differential area element is not as convenient as the other choices in this problem.

**Example 5:** Determine the moment of inertia with respect to the  $x$ -axis for the circular area shown in Figure (a)

**Solution I:** Using horizontal differential element, since

$$dA = 2x \cdot dy$$

we have

$$I_x = \int_A y^2 \cdot dA = \int_{-a}^a y^2 (2x) \cdot dy = 2 \int_{-a}^a y^2 \sqrt{a^2 - y^2} \cdot dy = 4 \int_0^a y^2 \sqrt{a^2 - y^2} \cdot dy$$

Using trigonometric substitutions:

$$\text{Let } y = a \sin \theta \quad dy = a \cos \theta \cdot d\theta$$

$$\int y^2 \sqrt{a^2 - y^2} \cdot dy = \int a^2 \sin^2 \theta \sqrt{a^2 - a^2 \sin^2 \theta} (a \cos \theta) \cdot d\theta$$

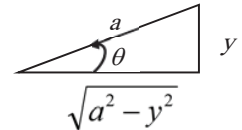
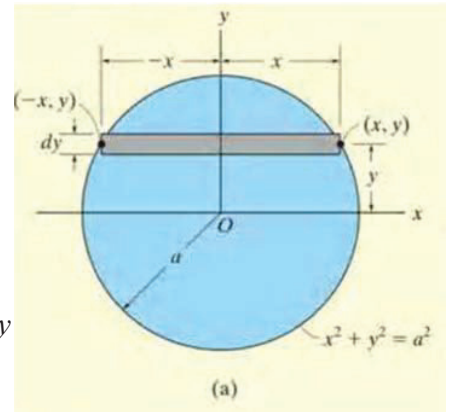
$$= a^4 \int \sin^2 \theta \cos^2 \theta \cdot d\theta = a^4 \int (\sin \theta \cos \theta)^2 \cdot d\theta = a^4 \int \left( \frac{\sin 2\theta}{2} \right)^2 \cdot d\theta$$

$$= \frac{a^4}{4} \int \left( \frac{1 - \cos 4\theta}{2} \right) d\theta = \frac{a^4}{8} \left[ \theta - \frac{\sin 4\theta}{4} \right] + C$$

$$= \frac{a^4}{8} \left[ \sin^{-1} \left( \frac{y}{a} \right) - \frac{\sin 4 \left( \sin^{-1} \left( \frac{y}{a} \right) \right)}{4} \right] + C$$

$$I_x = 4 \int_0^a y^2 \sqrt{a^2 - y^2} \cdot dy = \frac{4a^4}{8} \left[ \sin^{-1} \left( \frac{y}{a} \right) - \frac{\sin 4 \left( \sin^{-1} \left( \frac{y}{a} \right) \right)}{4} \right]_0^a$$

$$= \frac{4a^4}{8} \left[ \left( \sin^{-1}(1) - \frac{\sin 4(\sin^{-1}(1))}{4} \right) - \left( \sin^{-1}(0) - \frac{\sin 4(\sin^{-1}(0))}{4} \right) \right]$$



$$= \frac{a^4}{2} \left[ \left( \frac{\pi}{2} - \frac{\sin 4\left(\frac{\pi}{2}\right)}{4} \right) - (0-0) \right] = \frac{a^4}{2} \left( \frac{\pi}{2} - 0 \right) = \frac{\pi a^4}{4}$$

**Solution II:** When vertical differential element as shown in Figure (c) is chosen, the centroid for the element happens to lie on the  $x$ -axis, and since  $\bar{I}_x = \frac{bh^3}{12}$  for a rectangle, we have

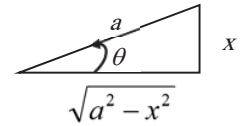
$$dI_x = \frac{(dx)(2y)^3}{12} = \frac{2}{3}y^3 dx = \frac{2}{3}(a^2 - x^2)^{3/2} .dx$$

Integrating with respect to  $x$  yields

$$I_x = \int_{-a}^a \frac{2}{3}(a^2 - x^2)^{3/2} .dx = 2 \int_0^a \frac{2}{3}(a^2 - x^2)^{3/2} .dx = \frac{4}{3} \int_0^a (a^2 - x^2)^{3/2} .dx$$

By trigonometric substitutions

$$\text{Let } x = a \sin \theta \quad dx = a \cos \theta .d\theta$$



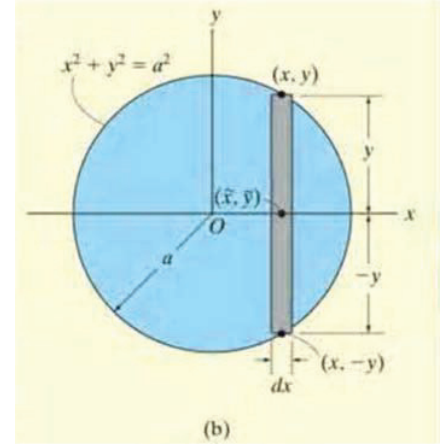
$$\int (a^2 - x^2)^{3/2} dx = \int (a^2 - a^2 \sin^2 \theta)^{3/2} a \cos \theta .d\theta = a^4 \int \cos^4 \theta .d\theta$$

$$= a^4 \int \left( \frac{1 + \cos 2\theta}{2} \right)^2 d\theta = \frac{a^4}{4} \int (1 + 2\cos 2\theta + \cos^2 2\theta) d\theta$$

$$= \frac{a^4}{4} \int \left( 1 + 2\cos 2\theta + \frac{1 + \cos 4\theta}{2} \right) d\theta = \frac{a^4}{4} \int \left( \frac{3}{2} + 2\cos 2\theta + \frac{\cos 4\theta}{2} \right) d\theta$$

$$= \frac{a^4}{4} \left[ \frac{3}{2}\theta + \frac{2\sin 2\theta}{2} + \frac{\sin 4\theta}{(2)(4)} \right] + C = \frac{a^4}{4} \left[ \frac{3}{2}\theta + 2\sin \theta \cos \theta + \frac{\sin 4\theta}{8} \right] + C$$

$$= \frac{a^4}{4} \left[ \frac{3}{2} \sin^{-1} \left( \frac{x}{a} \right) + 2 \left( \frac{x}{a} \right) \left( \frac{\sqrt{a^2 - x^2}}{a} \right) + \frac{\sin 4 \left( \sin^{-1} \left( \frac{x}{a} \right) \right)}{8} \right] + C$$

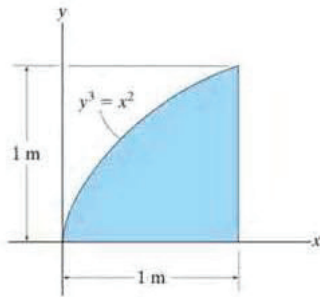




$$\begin{aligned}
 I_x &= \frac{4}{3} \int_0^a (a^2 - x^2)^{3/2} \cdot dx = \left(\frac{4}{3}\right) \left(\frac{a^4}{4}\right) \left[ \frac{3}{2} \sin^{-1}\left(\frac{x}{a}\right) + \left(\frac{2x\sqrt{a^2 - x^2}}{a^2}\right) + \frac{\sin 4\left(\sin^{-1}\left(\frac{x}{a}\right)\right)}{8} \right]_0^a \\
 &= \frac{a^4}{3} \left[ \left( \frac{3}{2} \sin^{-1}(1) + (0) + \frac{\sin 4(\sin^{-1}(1))}{8} \right) - \left( \frac{3}{2} \sin^{-1}(0) + (0) + \frac{\sin 4(\sin^{-1}(0))}{8} \right) \right] \\
 &= \frac{a^4}{3} \left[ \left( \frac{3}{2} \right) \left( \frac{\pi}{2} \right) \right] = \frac{\pi a^4}{4}
 \end{aligned}$$

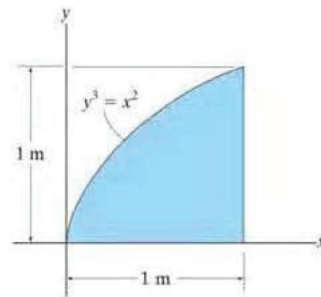
**Note:** By comparison, Solution I requires much less computations. Therefore, if an integral using a particular element appears difficult to evaluate, try solving the problem using an element oriented in the other direction.

**F10-1.** Determine the moment of inertia of the shaded area about the  $x$  axis.



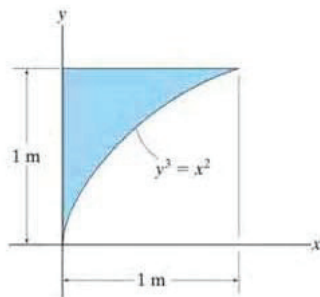
F10-1

**F10-3.** Determine the moment of inertia of the shaded area about the  $y$  axis.



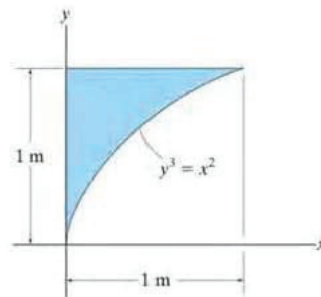
F10-3

**F10-2.** Determine the moment of inertia of the shaded area about the  $x$  axis.



F10-2

**F10-4.** Determine the moment of inertia of the shaded area about the  $y$  axis.



F10-4

## 5.6 Moment of Inertia for Composite Areas

A composite area consists of a series of connected "simpler" parts or shapes, such as rectangles, triangles and circles. Provided the moment of inertia of each of these parts is known or can be determined about a common axis, then the moment of inertia for the composite area about this axis equals the ***algebraic sum*** of the moments of inertia of all its part.

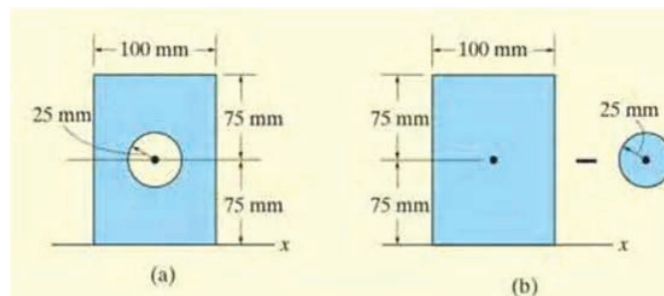
### Procedure for Analysis:

The moment of inertia for a composite area about a reference axis can be determined using the following procedure.

- Using a sketch, divide the area into its composite parts and indicate the perpendicular distance from the centroid of each part to the reference axis.
- If the centroid axis for each part does not coincide with the reference axis, the parallel-axis theorem,  $[I = \bar{I} + Ad^2]$  should be used to determine the moment of inertia of the part about the reference axis.
- The moment of inertia of the entire area about the reference axis is determined by summing the results of its composite parts about this axis.
- If a composite part has a "hole" its moment of inertia is found by "subtracting" the moment of inertia of the hole from the moment of inertia of the entire part including the hole.

<p><b>Rectangle</b></p> <p> <math>\bar{I}_x = \frac{bh^3}{12}</math>   <math>\bar{I}_y = \frac{b^3h}{12}</math>   <math>I_{xy} = 0</math>  <math>I_x = \frac{bh^3}{3}</math>   <math>I_y = \frac{b^3h}{3}</math>   <math>I_{xy} = \frac{b^2h^2}{4}</math> </p>	<p><b>Circle</b></p> <p> <math>I_x = I_y = \frac{\pi R^4}{4}</math>   <math>I_{xy} = 0</math> </p>	<p><b>Triangle</b></p> <p> <math>\bar{I}_x = \frac{bh^3}{36}</math>   <math>I_x = \frac{bh^3}{12}</math>  <math>\bar{I}_y = \frac{bh}{36}(a^2 - ab + b^2)</math>   <math>I_y = \frac{bh}{12}(a^2 + ab + b^2)</math>  <math>\bar{I}_{xy} = \frac{bh^2}{72}(2a - b)</math>   <math>I_{xy} = \frac{bh^2}{24}(2a + b)</math> </p>	<p><b>Half parabolic complement</b></p> <p> <math>\bar{I}_x = \frac{37bh^3}{2100}</math>   <math>I_x = \frac{bh^3}{21}</math>  <math>\bar{I}_y = \frac{bh^2}{80}</math>   <math>I_y = \frac{b^3h}{5}</math>  <math>\bar{I}_{xy} = \frac{b^2h^2}{120}</math>   <math>I_{xy} = -\frac{b^2h^2}{12}</math> </p>
<p><b>Right triangle</b></p> <p> <math>\bar{I}_x = \frac{bh^3}{36}</math>   <math>\bar{I}_y = \frac{b^3h}{36}</math>   <math>\bar{I}_{xy} = -\frac{b^2h^2}{72}</math>  <math>I_x = \frac{bh^3}{12}</math>   <math>I_y = \frac{b^3h}{12}</math>   <math>I_{xy} = \frac{b^2h^2}{24}</math> </p>	<p><b>Semicircle</b></p> <p> <math>\bar{I}_x = 0.1098R^4</math>   <math>\bar{I}_y = 0</math>  <math>I_x = I_y = \frac{\pi R^4}{8}</math>   <math>I_{xy} = 0</math> </p>	<p><b>Quarter circle</b></p> <p> <math>I_x = I_y = 0.05488R^4</math>   <math>I_x = I_y = \frac{\pi R^4}{16}</math>  <math>\bar{I}_{xy} = -0.01647R^4</math>   <math>I_{xy} = \frac{R^4}{8}</math> </p>	<p><b>Half parabola</b></p> <p> <math>\bar{I}_x = \frac{37bh^3}{175}</math>   <math>I_x = \frac{2bh^3}{7}</math>  <math>\bar{I}_y = \frac{13b^2h}{480}</math>   <math>I_y = \frac{2b^3h}{15}</math>  <math>\bar{I}_{xy} = \frac{b^2h^2}{60}</math>   <math>I_{xy} = \frac{b^2h^2}{6}</math> </p>
<p><b>Isosceles triangle</b></p> <p> <math>I_x = \frac{bh^3}{36}</math>   <math>\bar{I}_y = \frac{b^3h}{48}</math>   <math>\bar{I}_{xy} = 0</math>  <math>I_x = \frac{bh^3}{12}</math>   <math>I_{xy} = 0</math> </p>	<p><b>Quarter ellipse</b></p> <p> <math>I_x = 0.05488ab^3</math>   <math>I_x = \frac{\pi ab^3}{16}</math>  <math>\bar{I}_y = 0.05488a^3b</math>   <math>I_y = \frac{\pi a^3b}{16}</math>  <math>\bar{I}_{xy} = -0.01647a^2b^2</math>   <math>I_{xy} = \frac{a^2b^2}{8}</math> </p>	<p><b>Circular sector</b></p> <p> <math>I_x = \frac{R^4}{8}(2\alpha - \sin 2\alpha)</math>  <math>I_y = \frac{R^4}{8}(2\alpha + \sin 2\alpha)</math>  <math>I_{xy} = 0</math> </p>	

**Example 6:** Determine the moment of inertia of the area shown in Figure (a) about the x-axis



**Solution:** The area can be obtained by *subtracting* the circle from the rectangle shown in Figure (b). The centroid of each area is located in the Figure.

Circle

$$I_x = \bar{I}_x + Ad_y^2 = \frac{\pi(25)^4}{4} + \pi(25)^2(75)^2 = 11.4 \times 10^6 \text{ mm}^4$$

Rectangle

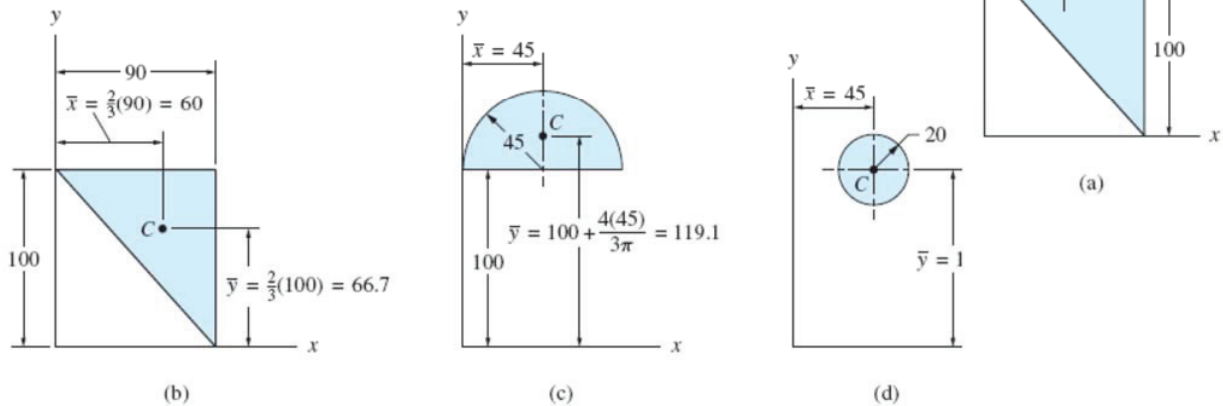
$$I_x = \bar{I}_x + Ad_y^2 = \frac{(100)(150)^3}{12} + (100)(150)(75)^2 = 112.5 \times 10^6 \text{ mm}^4$$

The moment of inertia for the area is therefore

$$I_x = 112.5 \times 10^6 - 11.4 \times 10^6 = 101 \times 10^6 \text{ mm}^4$$

**Example 7:** For the area shown in Fig. (a), calculate the radii of gyration about the  $x$ - and  $y$ -axes

**Solution:** We consider the area to be composed of the three parts shown in Figs. (b)–(d):

Triangle:

$$A = \frac{bh}{2} = \frac{90(100)}{2} = 4500 \text{ mm}^2$$

$$\bar{I}_x = \frac{bh^3}{36} = \frac{90(100)^3}{36} = 2.50 \times 10^6 \text{ mm}^4$$

$$I_x = \bar{I}_x + A(d_y)^2 = (2.50 \times 10^6) + (4500)(66.7)^2 = 22.52 \times 10^6 \text{ mm}^4$$

$$\bar{I}_y = \frac{hb^3}{36} = \frac{100(90)^3}{36} = 2.025 \times 10^6 \text{ mm}^4$$

$$I_y = \bar{I}_y + A(d_x)^2 = (2.025 \times 10^6) + (4500)(60)^2 = 18.23 \times 10^6 \text{ mm}^4$$

Semicircle:

$$A = \frac{\pi R^2}{2} = \frac{\pi(45)^2}{2} = 3181 \text{ mm}^2$$

$$\bar{I}_x = 0.1098R^4 = 0.1098(45)^4 = 0.450 \times 10^6 \text{ mm}^4$$

$$I_x = \bar{I}_x + A(d_y)^2 = (0.450 \times 10^6) + (3181)(119.1)^2 = 45.57 \times 10^6 \text{ mm}^4$$

$$\bar{I}_y = \frac{\pi R^4}{8} = \frac{\pi(45)^4}{8} = 1.61 \times 10^6 \text{ mm}^4$$

$$I_y = \bar{I}_y + A(d_x)^2 = (1.61 \times 10^6) + (3181)(45)^2 = 8.05 \times 10^6 \text{ mm}^4$$

Circle:

$$A = \pi R^2 = \pi(20)^2 = 1257 \text{ mm}^2$$

$$\bar{I}_x = \frac{\pi R^4}{4} = \frac{\pi(20)^4}{4} = 0.1257 \times 10^6 \text{ mm}^4$$

$$I_x = \bar{I}_x + A(d_y)^2 = (0.1257 \times 10^6) + (1257)(100)^2 = 12.70 \times 10^6 \text{ mm}^4$$

$$\bar{I}_y = \frac{\pi R^4}{4} = \frac{\pi(20)^4}{4} = 0.1257 \times 10^6 \text{ mm}^4$$

$$I_y = \bar{I}_y + A(d_x)^2 = (0.1257 \times 10^6) + (1257)(45)^2 = 2.67 \times 10^6 \text{ mm}^4$$

Composite Area

$$A = \Sigma A = 4500 + 3181 - 1257 = 6424 \text{ mm}^2$$

$$I_x = \Sigma I_x = (22.52 + 45.57 - 12.70) \times 10^6 = 55.39 \times 10^6 \text{ mm}^4$$

$$I_y = \Sigma I_y = (18.23 + 8.05 - 2.67) \times 10^6 = 23.61 \times 10^6 \text{ mm}^4$$

Therefore, for the radii of gyration we have

$$k_x = \sqrt{\frac{I_x}{A}} = \sqrt{\frac{55.39 \times 10^6}{6424}} = 92.9 \text{ mm}$$

$$k_y = \sqrt{\frac{I_y}{A}} = \sqrt{\frac{23.61 \times 10^6}{6424}} = 60.6 \text{ mm}$$