

**Example 2:** For the shown cantilever, find numerically the deflection at the free end.

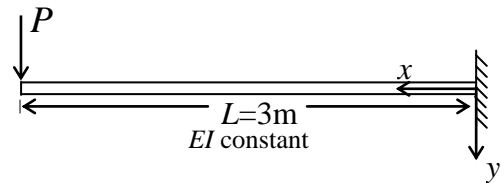
(Use  $h = 1$  m)

**Solution:**

$$EIy'' = -M.$$

From left,  $M = -P(L - x) \Rightarrow EIy'' = P(L - x),$

Or  $y'' = \frac{P}{EI}(3 - x), \quad y(0) = 0, \quad y'(0) = 0.$



**Solution I:** By using the 2<sup>nd</sup> order Runge-Kutta method which is of  $O(h)^2$ .

We must first transform the problem into a set of two 1<sup>st</sup> order ODEs.

Let  $y' = z \Rightarrow z' = \frac{P}{EI}(3 - x).$

Put  $f_1(z) = y' = z$  (which is used to find  $y$ ),

and  $f_2(x) = z' = \frac{P}{EI}(3 - x)$  (which is used to find  $z$ ).

$$y_{j+1} = y_j + h.(k_2)_1 \quad \text{and} \quad z_{j+1} = z_j + h.(k_2)_2 \quad \text{where,}$$

$$(k_1)_1 = f_1(x_j, y_j, z_j) \quad \text{and} \quad (k_2)_1 = f_1(x_j + \frac{h}{2}, y_j + \frac{h}{2}(k_1)_1, z_j + \frac{h}{2}(k_1)_2).$$

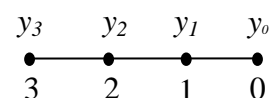
$$(k_1)_2 = f_2(x_j, y_j, z_j) \quad \text{and} \quad (k_2)_2 = f_2(x_j + \frac{h}{2}, y_j + \frac{h}{2}(k_1)_1, z_j + \frac{h}{2}(k_1)_2).$$

Since  $h = 1$  m, then we need three steps to move from the start point  $x = 0$  to the end point  $x = 3$  m.

**Step 1:**  $x_j = 0, \quad y_j = 0, \quad \text{and} \quad z_j = y'(x_j) = 0.$

$$(k_1)_1 = f_1(0,0,0) = 0,$$

$$(k_1)_2 = f_2(0,0,0) = \frac{P}{EI}(3 - 0) = \frac{3P}{EI},$$



$$(k_2)_1 = f_1\left(\left(0 + \frac{1}{2}\right), \left(0 + \frac{1}{2} \times 0\right), \left(0 + \frac{1}{2} \times \frac{3P}{EI}\right)\right) = f_1\left(\frac{1}{2}, 0, \frac{3P}{2EI}\right) = \frac{3P}{2EI},$$

$$(k_2)_2 = f_2\left(\frac{1}{2}, 0, \frac{3P}{2EI}\right) = \frac{P}{EI}\left(3 - \frac{1}{2}\right) = \frac{5P}{2EI},$$

$$\therefore y_1 = 0 + (1)\left(\frac{3P}{2EI}\right) = \frac{3P}{2EI}, \quad (\text{deflection at } x = 1 \text{ m})$$

$$\therefore z_1 = 0 + (1)\left(\frac{5P}{2EI}\right) = \frac{5P}{2EI}. \quad (\text{slope at } x = 1 \text{ m})$$

Step 2:  $x_j = 1, \quad y_j = \frac{3P}{2EI}, \quad \text{and} \quad z_j = \frac{5P}{2EI}.$

$$(k_1)_1 = f_1\left(1, \frac{3P}{2EI}, \frac{5P}{2EI}\right) = \frac{5P}{2EI},$$

$$(k_1)_2 = f_2\left(1, \frac{3P}{2EI}, \frac{5P}{2EI}\right) = \frac{P}{EI}(3 - 1) = \frac{2P}{EI},$$

$$(k_2)_1 = f_1\left(\left(1 + \frac{1}{2}\right), \dots, \left(\frac{5P}{2EI} + \frac{1}{2} \times \frac{2P}{EI}\right)\right) = f_1\left(\frac{3}{2}, \dots, \frac{7P}{2EI}\right) = \frac{7P}{2EI},$$

$$(k_2)_2 = f_2\left(\frac{3}{2}, \dots, \frac{7P}{2EI}\right) = \frac{P}{EI}\left(3 - \frac{3}{2}\right) = \frac{3P}{2EI},$$

$$\therefore y_2 = \frac{3P}{2EI} + (1)\left(\frac{7P}{2EI}\right) = \frac{5P}{EI}, \quad (\text{deflection at } x = 2 \text{ m})$$

$$\therefore z_2 = \frac{5P}{2EI} + (1)\left(\frac{3P}{2EI}\right) = \frac{4P}{EI}. \quad (\text{slope at } x = 2 \text{ m})$$

Step 3:  $x_j = 2, \quad y_j = \frac{5P}{EI}, \quad \text{and} \quad z_j = \frac{4P}{EI}.$

$$(k_1)_1 = f_1\left(2, \frac{5P}{EI}, \frac{4P}{EI}\right) = \frac{4P}{EI},$$

$$(k_1)_2 = f_2\left(2, \frac{5P}{EI}, \frac{4P}{EI}\right) = \frac{P}{EI}(3 - 2) = \frac{P}{EI},$$

$$(k_2)_1 = f_1\left(\left(2 + \frac{1}{2}\right), \dots, \left(\frac{4P}{EI} + \frac{1}{2} \times \frac{P}{EI}\right)\right) = f_1\left(\frac{5}{2}, \dots, \frac{9P}{2EI}\right) = \frac{9P}{2EI},$$

$$(k_2)_2 = f_2\left(\frac{5}{2}, \dots, \frac{9P}{2EI}\right) = \frac{P}{EI}\left(3 - \frac{5}{2}\right) = \frac{P}{2EI},$$

$$\therefore y_3 = \frac{5P}{EI} + (1)\left(\frac{9P}{2EI}\right) = \frac{19P}{2EI}, \quad (\text{deflection at } x = 3 \text{ m})$$

$$\therefore z_3 = \frac{4P}{EI} + (1)\left(\frac{P}{2EI}\right) = \frac{9P}{2EI}. \quad (\text{slope at } x = 3 \text{ m})$$

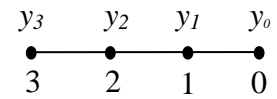
$\therefore$  The deflection at the free end is  $y_3 \approx \frac{19P}{2EI}.$

**Solution II:** By using the finite differences approximations:

For the obtained ODE, using central finite differences of  $O(h)^2$  we get,

$$f''_j = \frac{f_{j-1} - 2f_j + f_{j+1}}{h^2}, \text{ substituting this derivative into the ODE yields,}$$

$$\frac{y_{j-1} - 2y_j + y_{j+1}}{h^2} = \frac{P}{EI}(3 - x_j),$$



(Three unknowns:  
 $y_1, y_2,$  and  $y_3$ )

$$\therefore y_{j-1} - 2y_j + y_{j+1} = \frac{Ph^2}{EI}(3 - x_j)$$

At  $x_j = 1$ , (Note: from the first condition  $y_0 = y(0) = 0$ )

$$y_0 - 2y_1 + y_2 = \frac{P(1)^2}{EI}(3 - 1) \Rightarrow -2y_1 + y_2 = \frac{2P}{EI} \quad \dots\dots(1)$$

At  $x_j = 2$ ,

$$y_1 - 2y_2 + y_3 = \frac{P(1)^2}{EI}(3 - 2) \Rightarrow y_1 - 2y_2 + y_3 = \frac{P}{EI} \quad \dots\dots(2)$$

For the second condition  $y'(0) = 0$ , using forward differences of  $O(h)^2$ , we get,

$$f'_j = \frac{-3f_j + 4f_{j+1} - f_{j+2}}{2h}, \text{ substituting into the 2<sup>nd</sup> condition yields:}$$

$$\frac{-3y_0 + 4y_1 - y_2}{2h} = 0 \Rightarrow 4y_1 - y_2 = 0 \quad \dots\dots(3)$$

In matrix form: 
$$\begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 4 & -1 & 0 \end{bmatrix} \begin{Bmatrix} y_1 \\ y_2 \\ y_3 \end{Bmatrix} = \begin{Bmatrix} 2P/EI \\ P/EI \\ 0 \end{Bmatrix}.$$

Use Cramer's rule:

$$y_3 = \frac{\begin{vmatrix} -2 & 1 & 2P/EI \\ 1 & -2 & P/EI \\ 4 & -1 & 0 \end{vmatrix}}{\begin{vmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 4 & -1 & 0 \end{vmatrix}} = \frac{\frac{2P}{EI} \begin{vmatrix} 1 & -2 \\ 4 & -1 \end{vmatrix} + (-1) \frac{P}{EI} \begin{vmatrix} -2 & 1 \\ 4 & -1 \end{vmatrix} + 0}{0 + (-1)(1) \begin{vmatrix} -2 & 1 \\ 4 & -1 \end{vmatrix} + 0} = \frac{\frac{14P}{EI} + \frac{2P}{EI}}{2} = \frac{8P}{EI}.$$

$\therefore$  The deflection at the free end is  $y_3 \approx \frac{8P}{EI}$ .

## II- Solution of boundary value problems

To solve this type of ordinary differential equations, finite differences approximations are used.

**Example 1:** Find  $y(2)$  and  $y(3)$ : (Use  $h=1$ )

$$x^2 \frac{d^2 y}{dx^2} + x \frac{dy}{dx} - y = 0, \quad y(1) = 6, \quad y(4) = 9.$$

**Solution:**

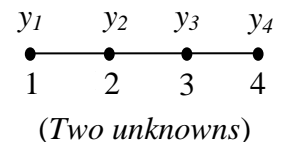
By using the finite differences approximations:

For the given ODE, using central finite differences approximations of  $O(h)^2$  we get,

$$x_j^2 \left( \frac{y_{j-1} - 2y_j + y_{j+1}}{h^2} \right) + x_j \left( \frac{-y_{j-1} + y_{j+1}}{2h} \right) - y_j = 0,$$

$$x_j^2 (y_{j-1} - 2y_j + y_{j+1}) + \frac{hx_j}{2} (-y_{j-1} + y_{j+1}) - h^2 y_j = 0,$$

$$(x_j^2 - \frac{hx_j}{2}) y_{j-1} - (2x_j^2 + h^2) y_j + (x_j^2 + \frac{hx_j}{2}) y_{j+1} = 0.$$



At  $x_j = 2$ , (Note: from the given conditions  $y_1 = 6$  and  $y_4 = 9$ )

$$(2^2 - \frac{1 \times 2}{2}) y_1 - (2 \times 2^2 + 1^2) y_2 + (2^2 + \frac{1 \times 2}{2}) y_3 = 0,$$

$$3(6) - 9y_2 + 5y_3 = 0 \quad \Rightarrow \quad -9y_2 + 5y_3 = -18. \quad \dots\dots(1)$$

At  $x_j = 3$ ,

$$(3^2 - \frac{1 \times 3}{2}) y_2 - (2 \times 3^2 + 1^2) y_3 + (3^2 + \frac{1 \times 3}{2}) y_4 = 0,$$

$$7.5y_2 - 19y_3 + 10.5(9) = 0 \quad \Rightarrow \quad 7.5y_2 - 19y_3 = -94.5. \quad \dots\dots(2)$$

In matrix form: 
$$\begin{bmatrix} -9 & 5 \\ 7.5 & -19 \end{bmatrix} \begin{Bmatrix} y_2 \\ y_3 \end{Bmatrix} = \begin{bmatrix} -18 \\ -94.5 \end{bmatrix}.$$

Use Cramer's rule:

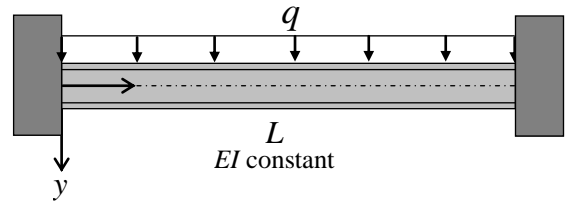
$$y_2 = \frac{\begin{vmatrix} -18 & 5 \\ -94.5 & -19 \end{vmatrix}}{\begin{vmatrix} -9 & 5 \\ 7.5 & -19 \end{vmatrix}} = \frac{-18(-19) - 5(-94.5)}{-9(-19) - 5(7.5)} = \frac{814.5}{133.5} = 6.101124.$$

$$y_3 = \frac{\begin{vmatrix} -9 & -18 \\ 7.5 & -94.5 \end{vmatrix}}{\begin{vmatrix} -9 & 5 \\ 7.5 & -19 \end{vmatrix}} = \frac{-9(-94.5) - (-18)(7.5)}{133.5} = \frac{985.5}{133.5} = 7.382023.$$

Note: The analytical solution is  $y = \frac{4}{x} + 2x \Rightarrow y(2) = 6$  and  $y(3) = 7.333333$ .

**Example 2:** Estimate, numerically, the deflection at midspan. (Use  $h = L/4$ )

**Solution:**



$$EI \frac{d^4 y}{dx^4} = w \Rightarrow EI \frac{d^4 y}{dx^4} = q$$

or  $\frac{d^4 y}{dx^4} = \frac{q}{EI}$ ,  $y(0) = 0$ ,  $y'(0) = 0$ ,  $y(L) = 0$ , and  $y'(L) = 0$ .

By using the finite differences approximations:

For the obtained ODE, using central finite differences of  $O(h)^2$  we get,

$$\frac{f_{j-2} - 4f_{j-1} + 6f_j - 4f_{j+1} + f_{j+1}}{h^4}, \text{ substituting into the ODE yields:}$$

$$\frac{y_{j-2} - 4y_{j-1} + 6y_j - 4y_{j+1} + y_{j+1}}{h^4} = \frac{q_j}{EI}$$

or  $y_{j-2} - 4y_{j-1} + 6y_j - 4y_{j+1} + y_{j+1} = \frac{q_j h^4}{EI}$ .

At  $x_j = L/2$ , (Note: from the conditions  $y_0 = 0$  and  $y_L = 0$ )

$$y_0 - 4y_{L/4} + 6y_{L/2} - 4y_{3L/4} + y_L = \frac{q(L/4)^4}{EI}$$

$$\therefore -4y_{L/4} + 6y_{L/2} - 4y_{3L/4} = \frac{qL^4}{256EI} \dots\dots\dots(1)$$

For the condition  $y'(0) = 0$ , using forward differences of  $O(h)^2$ , we get,

$$f'_j = \frac{-3f_j + 4f_{j+1} - f_{j+2}}{2h}, \text{ substituting into this condition yields:}$$

$$\frac{-3y_0 + 4y_{L/4} - y_{L/2}}{2h} = 0 \quad \Rightarrow \quad 4y_{L/4} - y_{L/2} = 0. \quad \dots\dots(2)$$

For the condition  $y'(L) = 0$ , using backward differences of  $O(h)^2$ , we get,

$$f'_j = \frac{3f_j - 4f_{j-1} + f_{j-2}}{2h}, \text{ substituting into this condition yields:}$$

$$\therefore \frac{3y_L - 4y_{3L/4} + y_{L/2}}{2h} = 0 \quad \Rightarrow \quad y_{L/2} - 4y_{3L/4} = 0. \quad \dots\dots(3)$$

In matrix form: 
$$\begin{bmatrix} -4 & 6 & -4 \\ 4 & -1 & 0 \\ 0 & 1 & -4 \end{bmatrix} \begin{Bmatrix} y_{L/4} \\ y_{L/2} \\ y_{3L/4} \end{Bmatrix} = \begin{bmatrix} qL^4 / 256EI \\ 0 \\ 0 \end{bmatrix}.$$

Use Cramer's rule:

$$y_{L/2} = \frac{\begin{vmatrix} -4 & \frac{qL^4}{256EI} & -4 \\ 4 & 0 & 0 \\ 0 & 0 & -4 \end{vmatrix}}{\begin{vmatrix} -4 & 6 & -4 \\ 4 & -1 & 0 \\ 0 & 1 & -4 \end{vmatrix}} = \frac{(-1)\frac{qL^4}{256EI} \begin{vmatrix} 4 & 0 \\ 0 & -4 \end{vmatrix} + 0}{-4 \begin{vmatrix} -1 & 0 \\ 1 & -4 \end{vmatrix} + (-1)(4) \begin{vmatrix} 6 & -4 \\ 1 & -4 \end{vmatrix} + 0} = \frac{\frac{qL^4}{16EI}}{64} = \frac{qL^4}{1024EI}.$$

$\therefore$  The deflection at midspan is  $y_{L/2} \approx \frac{qL^4}{1024EI}$ .