

#### University Of Basrah COLLEGE OF ENGINEERING MECHANICAL ENGINEERING DEPARTMENT



# **Resultants of system of forces**

The most common type of force system occurs when the forces all act in a single plane, say, the *x*-*y* plane, as illustrated by the system of three forces  $\mathbf{F_1}$ ,  $\mathbf{F_2}$ , and  $\mathbf{F_3}$  in Fig. 2/13*a*. We obtain the magnitude and direction of the resultant force **R** by forming the force polygon shown in part *b* of the figure, where the forces are added head-to-tail in any sequence. Thus, for any system of coplanar forces we may write:



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## **Principle of Moments**

This process is summarized in equation form by

$$\begin{cases} M_O \ge \sum \mathbf{F} \\ M_O \ge \sum \mathbf{M} = \sum (Fd) \\ Rd = MO \end{cases}$$
 (2/10)

The first two of Eqs. 2/10 reduce a given system of forces to a force-couple system at an arbitrarily chosen but convenient point *O*. *The last* equation specifies the distance *d* from point *O* to the line of action of **R**, and states that the moment of the resultant force about any point *O* equals the sum of the moments of the original forces of the system about the same point. This extends Varignon's theorem to the case of nonconcurrent force systems; we call this extension the principle of moments.

For a concurrent system of forces where the lines of action of all forces pass through a common point *O*, the moment sum SM about that point is zero. Thus, the line of action of the resultant  $\mathbf{R}=\Sigma\mathbf{F}$ , determined by the first of Eqs. 2/10, passes through point *O*. For a parallel force system, select a coordinate axis in the direction of the forces. If the resultant force  $\mathbf{R}$  for a given force system is zero, the resultant of the system need not be zero because the resultant may be a couple. The three forces in Fig. 2/15, for instance, have a zero resultant force but have a resultant clockwise couple  $M = F_3 d$ .

### SAMPLE PROBLEM 2/9

Determine the resultant of the four forces and one couple which act on the plate shown.



Figure 2/15

Solution: Point O is selected as a convenient reference point for the

force-couple system which is to represent the given system.  $\begin{bmatrix} R_x = \sum F_x \end{bmatrix} \qquad \begin{array}{l} R_x = 40 + 80\cos 30^\circ - 60\cos 45^\circ = 66.9 \ N \\ \begin{bmatrix} R_y = \sum F_y \end{bmatrix} \qquad \begin{array}{l} R_y = 50 + 80\sin 30^\circ + 60\sin 45^\circ = 132.4 \ N \\ \begin{bmatrix} R = \sqrt{F_x^2 + F_y^2} \end{bmatrix} \qquad \begin{array}{l} R = \sqrt{(66.9)^2 + (132.4)^2} = 148.3 \ N \\ \begin{bmatrix} \theta = \tan^{-1}\frac{R_y}{R_x} \end{bmatrix} \qquad \begin{array}{l} \theta = \tan^{-1}\frac{132.4}{66.9} = 63.2^\circ \\ \begin{bmatrix} M_o = \sum (Fd) \end{bmatrix} \qquad \begin{array}{l} M_o = 140 - 50(5) + 60\cos 45^\circ(4) - 60\sin 45^\circ(7) \end{array}$ 



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