

2.2 Normal AM System:

In this section the synchronous detection and the envelope detector is discussed to highlight the advantages of each of them.

A Synchronous Detection of AM:

$$x_c(t) = A_c [1 + \mu m(t)] \cos(2\pi f_c t)$$

$$x_c(t) = A_c \cos(2\pi f_c t) + A_c \mu m(t) \cos(2\pi f_c t)$$

$$\therefore S_i = \frac{A_c^2}{2} + \frac{A_c^2 \mu^2}{2} \overline{m^2(t)} \Rightarrow \boxed{S_i = \frac{A_c^2}{2} (1 + \mu^2 \overline{m^2(t)})}$$

$$y_i(t) = A_c (1 + \mu m(t)) \cos(2\pi f_c t) + n_p(t)$$

$$y_i(t) = A_c (1 + \mu m(t)) \cos(2\pi f_c t) + [n_i(t) \cos(2\pi f_c t) - n_q(t) \sin(2\pi f_c t)]$$

$$y(t) = y_i(t) * 2 \cos(2\pi f_c t)$$

$$y(t) = 2[A_c (1 + \mu m(t)) + n_i(t)] \cos^2(2\pi f_c t) - 2n_q(t) \sin(2\pi f_c t) \cos(2\pi f_c t)$$

$$y(t) = [A_c (1 + \mu m(t)) + n_i(t)] [1 + \cos(2\pi(2f_c)t)] - n_q(t) \sin(2\pi(2f_c)t)$$

After LPF with $BW = B$ Hz

$$y_o(t) = A_c (1 + \mu m(t)) + n_i(t) = \underbrace{A_c}_{DC} + \underbrace{A_c \mu m(t)}_{\text{signal}} + \underbrace{n_i(t)}_{\text{noise}}$$

After Blocking capacitor:

$$y_o(t) = A_c \mu m(t) + n_i(t)$$

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$$(S/N)_o = \frac{S_o}{N_o} = \frac{A_c^2 \mu^2 \overline{m^2(t)}}{2 \gamma B}$$

From the equation of S_i : $A_c^2 = \frac{2 S_i}{1 + \mu^2 \overline{m^2(t)}}$

$$\therefore (S/N)_o = \frac{2 S_i}{1 + \mu^2 \overline{m^2(t)}} \times \frac{\mu^2 \overline{m^2(t)}}{2 \gamma B}$$

$$\therefore (S/N)_o = \frac{\mu^2 \overline{m^2(t)}}{1 + \mu^2 \overline{m^2(t)}} \cdot \frac{S_i}{\gamma B}$$

$$\therefore \boxed{(S/N)_o = \frac{\mu^2 \overline{m^2(t)}}{1 + \mu^2 \overline{m^2(t)}} \gamma}$$

but we know that, $\mu^2 \overline{m^2(t)} \leq 1$, thus

$$\therefore (S/N)_o \leq \frac{1}{1+1} \gamma$$

$$\therefore \boxed{(S/N)_o \leq \frac{1}{2} \gamma} \quad (S/N)_{o \max} = \frac{1}{2} \gamma$$

This means that the best condition for the synchronous detection of AM signal is when $\mu^2 \overline{m^2(t)} = 1$, but it still 3dB lower than the DSB-SC detection.

The detection gain of the synchronous detection of normal AM modulation is given by:

$$\gamma_d = \frac{(S/N)_o}{(S/N)_i} = \frac{A_c^2 \mu^2 \overline{m^2(t)} / 2 \gamma B}{\frac{A_c^2}{2} A_c^2 [1 + \mu^2 \overline{m^2(t)}] / 2 \gamma B}$$

$$\boxed{\gamma_d = \frac{2 \mu^2 \overline{m^2(t)}}{1 + \mu^2 \overline{m^2(t)}}$$

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The best case when $\mu^2 \overline{m^2(t)} = 1$

$$\boxed{\gamma_{d \max} = 1} \quad \text{For synchronous detection of AM.}$$

Example: A speech signal is transmitted with ^{r.m.s value} ~~power~~ of 0.2 ~~Watt~~ ^{volt} using normal AM modulation with modulation index 0.5. The amplitude of the carrier signal is 10 volt, and the white noise power spectral density double side level ($\gamma/2 = 10^{-4}$ W/Hz). Find:

a) $(S/N)_0$ of the synchronous detection of the AM.

b) $(S/N)_0$ of the synchronous detection of DSB-SC modulation of the same signal. (Compare the results).
Assume the signal BW = B = 15 kHz.

Sol.

$$\overline{m^2(t)} = (0.2)^2 \text{ Watt}, \quad \mu = 0.5, \quad A_c = 10 \text{ Volt.}$$

$$\eta/2 = 10^{-4} \Rightarrow \eta = 2 \times 10^{-4} \text{ W/Hz}, \quad B = 15 \text{ kHz}$$

a) Normal AM:

$$S_i = \frac{A_c^2}{2} (1 + \mu^2 \overline{m^2(t)}) = \frac{100}{2} (1 + 0.5^2 \times 0.2^2)$$

$$\therefore S_i = 50.5 \text{ Watt}$$

$$\gamma = \frac{S_i}{\eta B} = \frac{50.5}{2 \times 10^{-4} \times 15 \times 10^3} \Rightarrow \gamma = 16.83$$

$$(S/N)_0 \text{ AM} = \frac{\mu^2 \overline{m^2(t)}}{1 + \mu^2 \overline{m^2(t)}} \gamma$$

$$(S/N)_0 \text{ AM} = \frac{0.5^2 \times 0.2^2}{1 + 0.5^2 \times 0.2^2} \times 16.83 \Rightarrow \boxed{(S/N)_{\text{AM}} = 0.167} \approx 0.167$$

b) DSB-SC:

$$S_i = \frac{A_c^2}{2} \overline{m^2(t)} = 2 \text{ Watt}$$

$$\gamma = \frac{S_i}{\eta B} = \frac{2}{2 \times 10^{-4} \times 15 \times 10^3}$$

$$\therefore \gamma = 0.667$$

$$(S/N)_0 \text{ DSB} = \gamma \Rightarrow \boxed{(S/N)_{\text{DSB}} = 0.667} \approx 0.6$$

Comparison: Although the input signal power of DSB ($S_i = 2 \text{ W}$) is much smaller than that of AM ($S_i = 50.5 \text{ W}$), DSB still has $(S/N)_0$ six times larger than $(S/N)_0$ of AM signal. This means that DSB is not only providing better SNR, but also power-efficient kind of modulation.

B Envelope Detection:

At the detector input, the AM signal plus noise signal is given by:

$$y_i(t) = A_c [1 + \mu m(t)] \cos(2\pi f_c t) + n_p(t)$$

OR

$$y_i(t) = A_c [1 + \mu m(t)] \cos(2\pi f_c t) + [n_i(t) \cos(2\pi f_c t) - n_q(t) \sin(2\pi f_c t)]$$

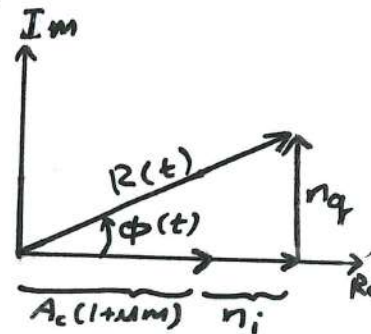
$$y_i(t) = [A_c(1 + \mu m(t)) + n_i(t)] \cos(2\pi f_c t) - n_q(t) \sin(2\pi f_c t)$$

The above equation can be re-written using phasor form:

$$y_i(t) = \underbrace{R(t)}_{\text{envelope}} \cos(2\pi f_c t + \phi(t))$$

where $R(t) = \sqrt{[A_c(1 + \mu m(t)) + n_i]^2 + n_q^2}$

$$\phi(t) = \tan^{-1} \frac{n_q}{A_c(1 + \mu m(t)) + n_i}$$



The input of the envelope detector is $R(t)$:

$$|y_i(t)| = \sqrt{[A_c(1 + \mu m(t)) + n_i]^2 + n_q^2} \quad \text{envelope of the signal.}$$

* If the signal is dominating the transmission:

$$\left(\frac{S}{N}\right)_i \gg 1 \quad \text{OR} \quad A_c(1 + \mu m) \gg n_i \& n_q$$

$$R(t) = [A_c(1 + \mu m(t)) + n_i] \sqrt{1 + \frac{n_q^2}{[A_c(1 + \mu m(t)) + n_i]^2}}$$

$$R(t) \approx A_c(1 + \mu m(t)) + n_i$$

$$R(t) = \underbrace{A_c}_{\text{DC}} + \underbrace{A_c \mu m(t)}_{\text{signal}} + \underbrace{n_i}_{\text{noise}}$$

After the D.C blocking capacitor.

$$R(t) = A_c \mu m(t) + n_i$$

$$\therefore y_0(t) = A_c \mu m(t) + n_i$$

The above $y_0(t)$ is the same as that obtained by the synchronous detection of AM signal, so

$$(S/N)_o = \frac{\mu^2 \overline{m^2(t)}}{1 + \mu^2 \overline{m^2(t)}} \gamma \quad \text{for } A_c(1 + \mu m(t)) \gg n_i \& n_q$$

* If the noise is dominating the signal envelope, the envelope will heavily be distorted, and the signal is lost. Therefore, $m(t)$ cannot be extracted from the signal envelope in this case.

Threshold Effect:

In some values of $(S/N)_i$, the signal distortion due to the noise is negligible.

* (γ_{th}) is the value of γ above which the condition $A_c(1 + \mu m(t)) \gg n_q \& n_i$ is applied.

Practically: $\gamma_{th} = 20$

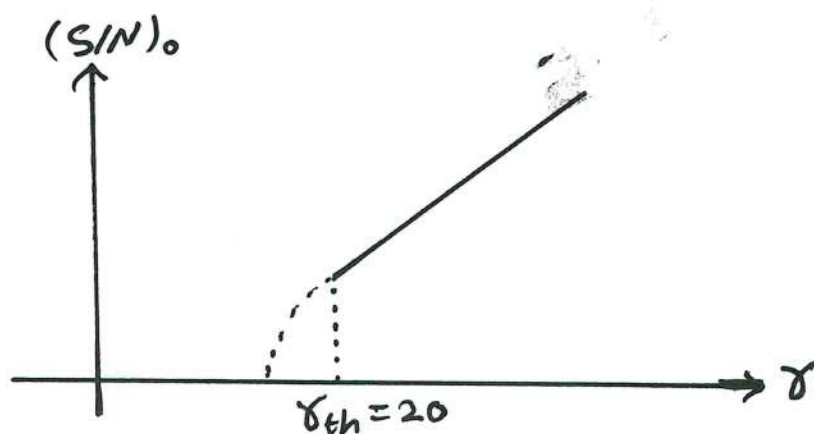
the best value of $(S/N)_{i,th} = \frac{\gamma_{th}}{2} = \frac{20}{2}$

$$(S/N)_{i,th} = 10$$

$$(S/N)_{i,th} \text{ (dB)} = 10 \text{ dB}$$

for $\mu = 1$

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2.3 SSB Systems:

$$x_c(t) = A_c [m(t) \cos(2\pi f_c t) \pm \hat{m}(t) \sin(2\pi f_c t)]$$

For the synchronous detection of SSB, the BPF has a bandwidth of $B \text{ Hz}$ instead of $2B \text{ Hz}$ in case of DSB-SC and AM systems.

$$S_i = \overline{x_c^2(t)} = \frac{A_c^2}{2} [\overline{m^2(t)} + \overline{\hat{m}^2(t)}]$$

$$\text{but } \overline{m^2(t)} = \overline{\hat{m}^2(t)}$$

$$\therefore \boxed{S_i = A_c^2 \overline{m^2(t)}}$$

$$y_i(t) = A_c [m(t) \cos(2\pi f_c t) + \hat{m}(t) \sin(2\pi f_c t)] + n_p(t)$$

$$y_i(t) = A_c [m(t) \cos(2\pi f_c t) + \hat{m}(t) \sin(2\pi f_c t)] + n_i(t) \cos(2\pi f_c t) - n_q(t) \sin(2\pi f_c t)$$

$$\therefore y_i(t) = (A_c m(t) + n_i) \cos(2\pi f_c t) + (A_c \hat{m}(t) - n_q) \sin(2\pi f_c t)$$

$$y(t) = y_i(t) \times 2 \cos(2\pi f_c t)$$

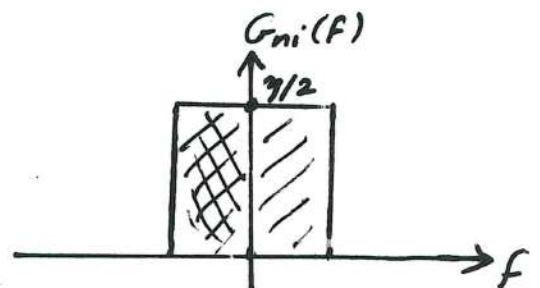
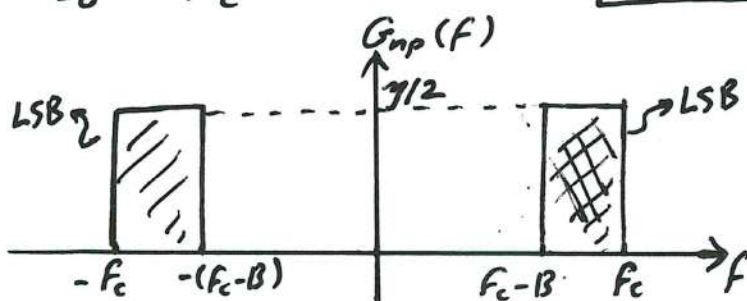
$$y(t) = 2(A_c m(t) + n_i) \cos^2(2\pi f_c t) + 2(A_c \hat{m}(t) - n_q) \sin(2\pi f_c t) \cos(2\pi f_c t)$$

$$y(t) = (A_c m(t) + n_i) + (A_c m(t) + n_i) \cos(2\pi(2f_c)t) + (A_c \hat{m}(t) - n_q) \sin(2\pi(2f_c)t)$$

After LPF with $BW = B \text{ Hz}$

$$y_o(t) = \underbrace{A_c m(t)}_{\text{signal}} + \underbrace{n_i(t)}_{\text{noise}}$$

$$\therefore S_o = A_c^2 \overline{m^2(t)} \Rightarrow \boxed{S_o = S_i}$$



$$N_o = \int_{-\infty}^{\infty} G_{ni}(f) df$$

$$N_o = \int_{-B}^B \frac{\gamma}{2} df \Rightarrow \boxed{N_o = \gamma B}$$

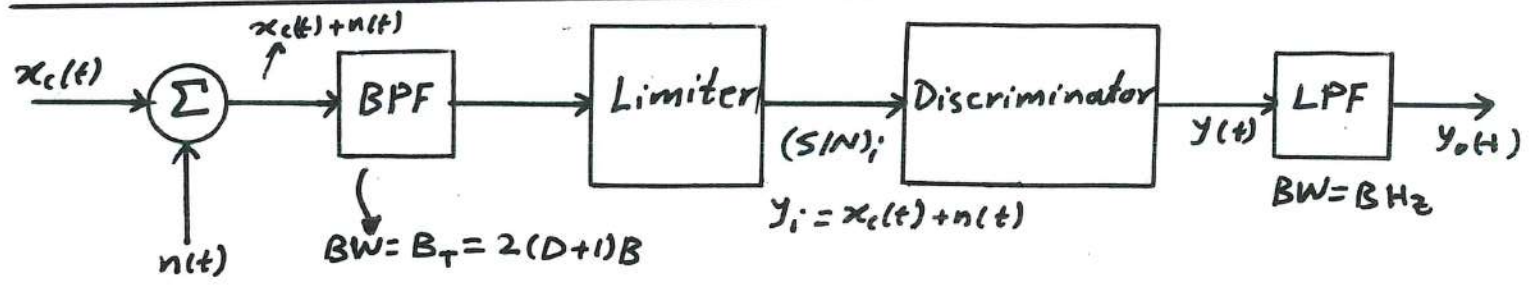
$$(S/N)_o = \frac{S_o}{N_o} = \frac{S_i}{\gamma B}$$

$$\therefore \boxed{(S/N)_o = \gamma} = (S/N)_i$$

$$\therefore \gamma_d = \frac{(S/N)_o}{(S/N)_i} \Rightarrow \boxed{\gamma_d = 1}$$

- SSB has the same $(S/N)_o$ as the DSB.
- VSB is exactly the same as SSB in noise calculations

3. Noise in Angle Modulation Systems:



$$x_c(t) = A_c \cos(2\pi f_c t + \phi(t)) = A_c \cos(\theta(t))$$

$$y_i(t) = x_c(t) + n(t) = A_c \cos(2\pi f_c t + \phi(t)) + n(t)$$

$$\boxed{S_i = \frac{A_c^2}{2}}$$

$$N_i = \overline{n^2(t)} = \int_{-(f_c + B_T/2)}^{-(f_c - B_T/2)} \frac{\gamma}{2} df + \int_{f_c - B_T/2}^{f_c + B_T/2} \frac{\gamma}{2} df$$

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$$\therefore \boxed{N_i = \gamma B_T} \Rightarrow \boxed{(S/N)_i = \frac{A_c^2}{2\gamma B_T}}$$

Since the noise is narrowband, it can be written as:

$$n(t) = R_n(t) \cos(2\pi f_c t + \phi_n(t))$$

which is the phasor form of $\{ n_i \cos(\omega_c t) - n_q \sin(\omega_c t) \}$

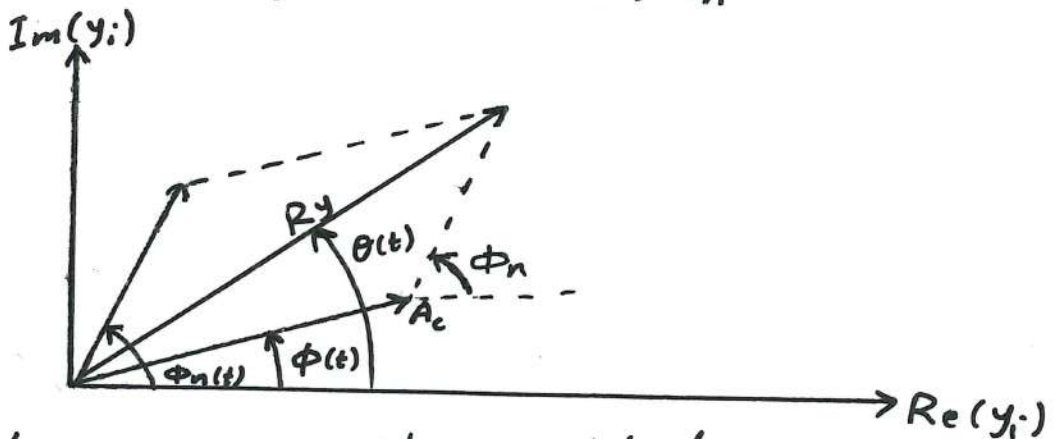
$$y_i(t) = A_c \cos [2\pi f_c t + \phi(t)] + R_n(t) \cos [2\pi f_c t + \phi_n(t)] \quad \text{--- (*)}$$

$$\therefore y_i(t) = R_y(t) \cos [2\pi f_c t + \theta(t)]$$

where

$$R_y(t) = \sqrt{(A_c \cos \phi + R_n \cos \phi_n)^2 + (A_c \sin \phi + R_n \sin \phi_n)^2}$$

$$\theta(t) = \tan^{-1} \left[\frac{A_c \sin \phi + R_n \sin \phi_n}{A_c \cos \phi + R_n \cos \phi_n} \right]$$

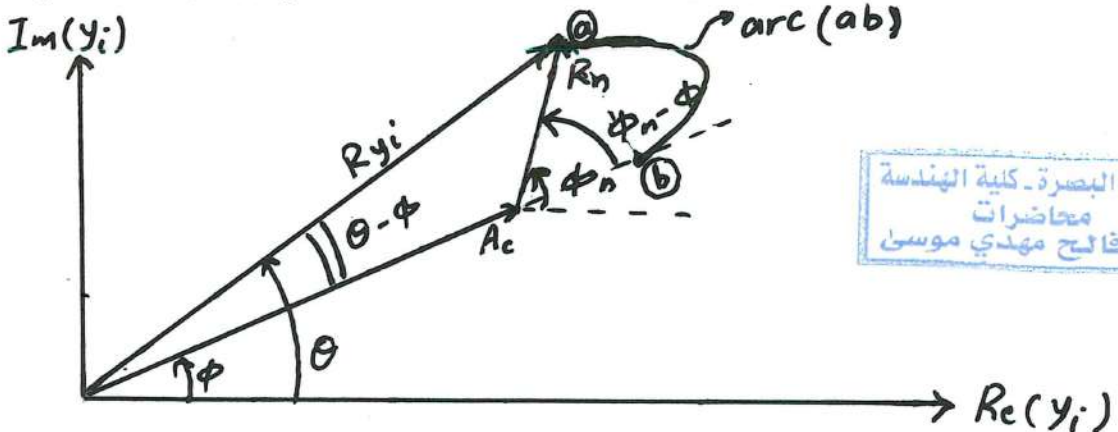


The limiter suppresses the amplitude $R_y(t)$ and keep it constant. Therefore, the $(SIN)_o$ is derived taking into account $\theta(t)$ only.

$$y_o(t) = \begin{cases} \theta(t) & \rightarrow \text{PM} \\ \frac{d\theta(t)}{dt} & \rightarrow \text{FM} \end{cases}$$

* If the signal is dominating the transmission:

$$(SIN)_i \gg 1 \quad , \quad A_c \gg R_n$$



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eq: (*) can be written as follows:

$$y_i(t) = \text{Re} [A_c e^{j\omega_c t} \cdot e^{j\phi(t)} + R_n(t) e^{j\omega_c t} \cdot e^{j\phi_n(t)}]$$

$$y_i(t) = \text{Re} [(A_c e^{j\phi(t)} + R_n e^{j\phi_n(t)}) e^{j\omega_c t}]$$

$$y_i(t) = \text{Re} [R_{y_i}(t) e^{j2\pi f_c t}]$$

where $R_{y_i}(t)$ is the envelope of $y_i(t)$.

$$R_{y_i}(t) = A_c e^{j\phi(t)} + R_n(t) e^{j\phi_n(t)} \quad \text{but } A_c \gg R_n(t)$$

The length of the arc (ab) is (L):

$$L = R_{y_i}(t) [\theta(t) - \phi(t)] \quad \{\text{arc length} = \text{radius} \times \text{angle}\}$$

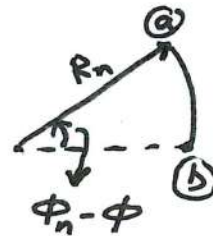
Since $A_c \gg R_n(t)$

$$\therefore R_{y_i}(t) \approx A_c + R_n \cos(\phi_n - \phi) \approx A_c$$

$$\therefore L \approx A_c [\theta(t) - \phi(t)]$$

From the noise triangle

$$L \approx R_n \sin(\phi_n - \phi)$$



$$\therefore A_c [\theta(t) - \phi(t)] = R_n \sin(\phi_n - \phi)$$

$$\text{or } \theta(t) \approx \frac{R_n}{A_c} \sin(\phi_n - \phi) + \phi(t)$$

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$$\therefore \boxed{\theta(t) \approx \phi(t) + \frac{n_s(t)}{A_c}} \quad n_s(t) = \frac{R_n}{A_c} \sin(\phi_n - \phi)$$

the output of the system is $y_o(t) = \begin{cases} \theta(t) & \text{PM} \\ \frac{d\theta}{dt} & \text{FM} \end{cases}$

$$\therefore y_o(t) = k_p m(t) + \frac{n_s(t)}{A_c} \quad \text{for PM}$$

$$y_o(t) = \underbrace{k_f m(t)}_{\text{Signal}} + \underbrace{\frac{n_s'(t)}{A_c}}_{\text{Noise}} \quad \text{for FM}$$

A (SIN)_o in PM Systems:

$$y_o(t) = \underbrace{k_p m(t)}_{\text{Signal}} + \underbrace{\frac{n_s(t)}{A_c}}_{\text{Noise}}$$

$$S_o = k_p^2 \overline{m^2(t)}$$

$$N_o = \frac{\overline{n_s^2(t)}}{A_c^2} = \frac{1}{A_c^2} \cdot \int_{-B}^B \gamma df \Rightarrow$$

$$N_o = \frac{2\gamma B}{A_c^2}$$

$$\therefore (SIN)_o = \frac{S_o}{N_o} = \frac{k_p^2 \overline{m^2(t)}}{\gamma B} \cdot \frac{A_c^2}{2}$$

$$\text{but } \frac{A_c^2}{2} = S_i$$

$$\therefore (SIN)_o = k_p^2 \overline{m^2(t)} \frac{S_i}{\gamma B}$$

remember that

$$\frac{S_i}{\gamma B} = \gamma$$

$$\therefore (SIN)_o = k_p^2 \overline{m^2(t)} \gamma$$

It is clear that the improvement of the (SIN)_o depends on the phase deviation constant (k_p) and the power of the message signal $\overline{m^2(t)}$.

where $k_{p \max} = \pi$.

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B (SIN)_o in FM Systems:

$$y_o(t) = \underbrace{k_f m(t)}_{\text{Signal}} + \underbrace{\frac{n'_s(t)}{A_c}}_{\text{Noise}}$$

$$S_o = k_f^2 \overline{m^2(t)}$$

$$n'_s(t) = \frac{d}{dt} (n_s(t))$$

$$F.T [n'_s(t)] = j2\pi f N_s(f)$$

Power spectral density of $n'_s(t)$ is $G'_{n_s}(f)$

$$G'_{n_s}(f) = |F.T [n'_s(t)]|^2$$