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Cite as: AIP Conference Proceedings **2086**, 030003 (2019); <https://doi.org/10.1063/1.5095088>
Published Online: 02 April 2019

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Constant Curvature of A Locally Conformal Almost Cosymplectic Manifold

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Abstract. The purpose of the present paper is to discuss the geometrical properties of a locally conformal almost cosymplectic manifold of constant curvature. In particular, the necessary and sufficient conditions for the aforementioned manifold to be of constant curvature have been determined.

Keywords: Locally conformal almost cosymplectic manifold; constant curvature.

PACS: 02.40.Ky

INTRODUCTION

The concept of a constant curvature is one of the important concepts in contact geometry. Blair [2] established that a cosymplectic manifold of constant curvature is locally flat. Moreover, Goldberg and Yano [5] obtained that an almost cosymplectic manifold of constant curvature is cosymplectic if and only if it is locally flat. Seo [11] exclusively, determined a classification of the translation hypersurfaces with a constant mean curvature in an Euclidean space.

PRELIMINARIES

This section provides a summary of the basic concepts and facts which are related to the discussion of our results.

Definition 0.1 [2] Let M be a $2n + 1$ dimensional smooth manifold, η be a differential 1-form called the contact form, ξ be a vector field called the characteristic vector field, Φ be an endomorphism of the module of the vector fields $X(M)$ called a structure endomorphism, then the triple (η, ξ, Φ) is called an almost contact structure if the following conditions hold

$$(1) \eta(\xi) = 1; (2) \Phi(\xi) = 0; (3) \eta \circ \Phi = 0; (4) \Phi^2 = -id + \eta \otimes \xi.$$

Moreover, if there is a Riemannian metric $g = \langle \cdot, \cdot \rangle$ on M such that $\langle \Phi X, \Phi Y \rangle = \langle X, Y \rangle - \eta(X)\eta(Y)$, $X, Y \in X(M)$, then the set of the tensors (η, ξ, Φ, g) is called an almost contact metric structure. In this case the manifold M equipped with this structure is called an almost contact metric manifold.

Definition 0.2 [9] At each point $p \in M^{2n+1}$, there is a frame in $T_p^c(M)$ of the form $(p, \varepsilon_0, \varepsilon_1, \dots, \varepsilon_n, \varepsilon_{\hat{1}}, \dots, \varepsilon_{\hat{n}})$, where $\varepsilon_a = \sqrt{2}\pi(e_a)$, $\varepsilon_{\hat{a}} = \sqrt{2}\pi(e_a)$, $\hat{a} = a + n$, $\varepsilon_0 = \xi_p$. The frame $(p, \varepsilon_0, \varepsilon_1, \dots, \varepsilon_n, \varepsilon_{\hat{1}}, \dots, \varepsilon_{\hat{n}})$ is called an A-frame. The set of such frames defines a G-structure on M with the structure group $1 \times U(n)$. This G-structure is called an adjointed G-structure space.

Lemma 0.1 [9] The matrices components of the tensors Φ_p and g_p in an A-frame have the following forms,

$$\text{respectively: } (\Phi_j^i) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & \sqrt{-1}I_n & o \\ 0 & 0 & -\sqrt{-1}I_n \end{pmatrix}, (g_{ij}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -I_n \\ 0 & I_n & 0 \end{pmatrix}, \text{ where } I_n \text{ is the identity matrix of order } n.$$

Definition 0.3 [5] An almost contact metric structure $S = (\eta, \xi, \Phi, g)$ is called an almost cosymplectic structure (\mathcal{AC}_f -structure) if the following conditions hold:

1. $d\eta = 0$;
2. $d\Omega = 0$.

Definition 0.4 [10] A conformal transformation of an \mathcal{AC} -structure $S = (\eta, \xi, \Phi, g)$ on a manifold is a transformation from S to an \mathcal{AC} -structure $\tilde{S} = (\tilde{\eta}, \tilde{\xi}, \tilde{\Phi}, \tilde{g})$ such that $\tilde{\eta} = e^{-\sigma}\eta$, $\tilde{\xi} = e^\sigma\xi$, $\tilde{\Phi} = \Phi$, $\tilde{g} = e^{-2\sigma}g$, where σ is a determining function of the conformal transformation.

Definition 0.5 [10] An \mathcal{AC} -structure S on a manifold M is said to be a locally conformal almost cosymplectic (\mathcal{LCAC}_f -structure) if the restriction of this structure to some neighborhood U of an arbitrary point $p \in M$ admits a conformal transformation of an almost cosymplectic structure. This transformation is called a locally conformal. A manifold M equipped with an \mathcal{LCAC}_f -structure is called a locally conformal almost cosymplectic manifold (\mathcal{LCAC}_f -manifold).

Lemma 0.2 [6] In the adjoined G -structure space, the Cartan structural equations of \mathcal{LCAC}_f -manifold have the following forms:

1. $d\omega^a = -\omega_b^a \wedge \omega^b + B_c^{ab} \omega^c \wedge \omega_b + B^{abc} \omega_b \wedge \omega_c + B_b^a \omega \wedge \omega^b + B^{ab} \omega \wedge \omega_b$;
2. $d\omega_a = \omega_a^b \wedge \omega_b + B_{ab}^c \omega_c \wedge \omega^b + B_{abc} \omega^b \wedge \omega^c + B_a^b \omega \wedge \omega_b + B_{ab} \omega \wedge \omega^b$;
3. $d\omega = C_b \omega \wedge \omega^b + C^b \omega \wedge \omega_b$;
4. $d\omega_b^a = -\omega_c^a \wedge \omega_b^c + A_b^{acd} \omega_c \wedge \omega_d + A_{bcd}^a \omega^c \wedge \omega^d + A_{bd}^{ac} \omega^d \wedge \omega_c + A_{bc0}^a \omega \wedge \omega^c + A_b^{ac0} \omega \wedge \omega_c$.

Here, B^{abc} , B_{abc} ; B^ab , B_{ab} ; B_a^b , B_b^a ; C^{ab} , C_{ab} ; C^b , C_b ; A_b^{acd} , A_{acd}^b ; A_{bd}^{ac} ; A_b^{ac0} , A_{ac0}^b ; B^{abci} , B_{abci} ; D^{abi} , D_{abi} and σ_{ij} are smooth functions in the adjoined G -structure space. B^{abc} are the components of the second structure tensor.

Lemma 0.3 [7] In the adjoined G -structure space, the components of the Riemannian curvature tensor of \mathcal{LCAC}_f -manifold have the following forms:

1. $R_{bcd}^a = 2(A_{bcd}^a + 4\sigma^{[a} \delta_{[c}^{h]} B_{d]hb} - \sigma_0 B_{b[ad} \delta_{c]}^a)$;
2. $R_{bcd}^a = 2(2\delta_{[c}^{[b} \sigma_{d]}^a] + 2B^{hab} B_{hdc} - \delta_{[c}^a \delta_{d]}^b \sigma_0^2)$;
3. $R_{bcd}^a = A_{bc}^{ad} + 4\sigma^{[a} \delta_c^{h]} \sigma_{[h} \delta_{b]}^d - 4B^{dah} B_{chb} + B^{ad} B_{bc} - \delta_c^a \delta_b^d \sigma_0^2$;
4. $R_{bcd}^a = 2(2B_{[c[ab]d]} - 2\sigma_{[a} B_{b]cd} + B_{a[c} B_{d]b})$;
5. $R_{0cd}^a = 2(\sigma_{0[c} \delta_{d]}^a + B^{ab} B_{bcd} - 2\sigma^{[a} \delta_{[c}^{h]} B_{d]h})$;
6. $R_{bc0}^a = A_b^{ac0} + \sigma_b B^{ac} - \delta_b^c \sigma_0 \sigma^a$;
7. $R_{bc0}^a = 2B_{cab0} + 2B_{cab} \sigma_0$;
8. $R_{0b0}^a = -\delta_b^a \sigma_{00} - \delta_b^a \sigma_0^2 - B_{cb} B^{ac} - \sigma_b^a - \sigma^a \sigma_b + 2\sigma^{[a} \delta_b^c] \sigma_c$;
9. $R_{0b0}^a = 2\sigma_0 B^{ab} - D^{ab0} - \sigma^{ab} - \sigma^a \sigma^b + 2B^{bac} \sigma_c$.

and the other components are conjugate to the above components or can be obtained by the properties of symmetry for R or are equal to zero.

Definition 0.6 [7] An almost contact manifold is called a Kenmotsu manifold if the equality

$$\nabla_X(\Phi)Y = \langle X, Y \rangle \xi - \eta(Y)X;$$

holds for each $X, Y \in X(M)$

Definition 0.7 [4] The Ricci tensor is a tensor of type $(2, 0)$ which is defined by $r_{ij} = -R_{ijk}^k$.

Lemma 0.4 [1] In the adjoined G -structure space, the components of the Ricci tensor of \mathcal{LCAC}_f -manifold are given as follows:

1. $r_{ab} = 2(-2A_{(ab)c}^c - 4(\sigma^{[c} \delta_{[b}^{h]} B_{c]ha} + \sigma^{[c} \delta_{[a}^{h]} B_{c]hb}) + \sigma_0 B_{a[c} \delta_{b]}^c + \sigma_0 B_{b[c} \delta_{a]}^c + 2\sigma_0 B_{ab} - D_{ab0} - \sigma_{ab} - \sigma_a \sigma_b + 2B_{bah} \sigma^h$;

2. $r_{\hat{a}\hat{b}} = -4(\delta_{[b}^{[a}\sigma_{c]}^c] - \sigma_{[c}\delta_{\hat{h}]}\sigma^{[h}\delta_c^{a]} - \frac{1}{2}\sigma^{[a}\delta_b^{h]} \sigma_h + B^{hca}B_{hcb} + B^{bch}B_{cha}) + (B^{cb}B_{ac} - B_{hb}B^{ah}) + A_{ac}^{cb} - \delta_b^a\sigma_{00} - 2n\sigma_0^2 - \sigma_b^a - \sigma^a\sigma_b$;
3. $r_{a0} = -A_{ac0}^c - \sigma^c B_{ac} + n\sigma_0\sigma_a + 2(\sigma_{0[c}\delta_{a]}^c + B^{cb}B_{bca} - 2\sigma^{[c}\delta_{[c}^{h]}B_{a]h})$;
4. $r_{oo} = -2n(\sigma_{00} + \sigma_0^2) - 2B_{hc}B^{ch} - 2(\sigma_c^c + \sigma^c\sigma_c) + 4\sigma^{[c}\delta_c^{h]} \sigma_h$.

and the other components can be obtain by taking the conjugate operator to the above components.

Definition 0.8 [8] An \mathcal{AC} -manifold is said to be of constant curvature k , if the Riemannian curvature tensor satisfies the relations $R_{ijkl} = k(g_{ik}g_{jl} - g_{il}g_{jk})$.

Lemma 0.5 [8] In the G -adjoined structure space, the nonzero components of the Riemannian curvature tensor of a manifold M of constant curvature have the forms

$$R_{\hat{a}\hat{b}\hat{c}\hat{d}} = k\delta_{\hat{c}\hat{d}}^{\hat{a}\hat{b}} \quad R_{\hat{a}bc\hat{d}} = k\delta_c^a\delta_d^b \quad R_{\hat{a}0c0} = k\delta_c^a \quad .$$

Definition 0.9 [8] The manifolds of constant curvature are called the special forms. The manifolds of zero constant curvature are said to be planes.

Definition 0.10 [3] A pseudo-Riemannian manifold M is called an η -Einstein manifold of type (α, β) if its Ricci tensor satisfies the equation $r = \alpha g + \beta \eta \otimes \eta$, where α and β are suitable smooth functions. If $\beta = 0$, then M is called an Einstein manifold.

Definition 0.11 The Riemannian curvature tensor of \mathcal{LCA}_f -manifold has the first special property, if

$$\eta \circ R(\Phi^2 X, \Phi^2 Y)\Phi^2 Z = \eta \circ (R(\Phi X, \Phi Y)\Phi^2 Z + R(\Phi^2 X, \Phi Y)\Phi Z + R(\Phi X, \Phi^2 Y)\Phi Z);$$

hold for each $X, Y, Z \in X(M)$.

Definition 0.12 The Riemannian curvature tensor of \mathcal{LCA}_f -manifold has the second special property, if

$$\eta \circ [R(\Phi^2 X, \xi)\Phi^2 Y + \eta \circ (R(\Phi X, \xi)\Phi Y)] = 0;$$

hold for each $X, Y, \xi \in X(M)$.

THE MAIN RESULTS

Theorem 0.1 The necessary and sufficient conditioni for a \mathcal{LCA}_f to be a manifold of constant curvature k is $A_{bc}^{ad} = B^{abc} = B^{ab} = \sigma^a = \sigma_{00} = 0$. Moreover, $k = -\sigma_0^2$.

Proof. Comparing the components of the Riemannian curvature tensor in the Lemmas 0.3 and 0.5, we have

$$2(2\delta_{[c}^{[b}\sigma_{d]}^a] + 2B^{hab}B_{hdc} - \delta_{[c}^a\delta_{d]}^b\sigma_0^2) = k\delta_{cd}^{\hat{a}\hat{b}} \quad .$$

Consequently, we get

$$k = -\sigma_0^2 \quad .$$

Moreover, we have

$$A_{bc}^{ad} + 4\sigma^{[a}\delta_c^{h]} \sigma_{[h}\delta_b^d] - 4B^{dah}B_{chb} + B^{ad}B_{bc} - \delta_c^a\delta_b^d\sigma_0^2 = k\delta_c^a\delta_d^b \quad .$$

Making use of the equality $R_{bcd}^{\hat{a}} = 0$, consequently we obtain

$$A_{bc}^{ad} = 0 \quad .$$

Now, according to the Lemma 0.3, item 3, it follows that $B^{abc} = 0$.

According to the relation $R_{0c0}^a = R_{\hat{a}0c0}$, we get

$$-\delta_c^a\sigma_{00} - \delta_c^a\sigma_0^2 - B_{hb}B^{ah} - \sigma_c^a - \sigma^a\sigma_c + 2\sigma^{[a}\delta_c^{h]} \sigma_h = k\delta_c^a \quad .$$

Now, making use of $R_{0\hat{b}0}^a = 0$, we get $\sigma^a\sigma^b = 0$ and according to the Lemma 0.2, items 9 and 10, we have $\sigma_a^a = 0$, which means

$$\sigma_{00} = 0 \quad .$$

Conversely, we can get the requirement directly from the lemmas 0.2 and 2.3. □

Theorem 0.2 The \mathcal{LCA}_f -manifold M which is a special form has nonpositive curvature. Moreover,
(1) M is a conformally flat Kenmotsu manifold if and only if $k = -1$;
(2) If $k = 0$, then M is a locally flat cosymplectic manifold.

Theorem 0.3 Suppose that a \mathcal{LCA}_f -manifold M is an η -Einstein manifold of type (α, β) , then $\alpha = \frac{1}{n}A_{ac}^{(ca)} - \sigma_{00} - 2n\sigma_0^2 - \frac{1}{n}(\sigma_a^a + \sigma^a\sigma_a)$ and $\beta = -\frac{1}{n}A_{ac}^{(ca)} - (2n-1)\sigma_{00} + (\frac{1}{n}-2)(\sigma_a^a + \sigma^a\sigma_a)$ hold. In addition, if M is a manifold of constant curvature, then M is an Einstein manifold with a cosmological constant $\alpha = -2n\sigma_0^2$.

Proof. Comparing the components of the Ricci tensor in the Lemma 0.3 and 0.5, we have

$$-4(\delta_{[b}^{[a}\sigma_{c]}^c] - \sigma_{[c}\delta_{h]}^b\sigma^{[h}\delta_c^{a]}) - \frac{1}{2}\sigma^{[a}\delta_b^{h]}\sigma_h + B^{hca}B_{hcb} + B^{bch}B_{cha} \\ + (B^{cb}B_{ac} - B_{hb}B^{ah}) + A_{ac}^{cb} - \delta_b^a\sigma_{00} - 2n\sigma_0^2 - \sigma_b^a - \sigma^a\sigma_b = \alpha\delta_b^a \quad (0.1)$$

Symmtrizing and antisymmtrizing (0.1) by the indices (a, h) and then symmtrizing by the indices (b, c) , we get

$$A_{ac}^{(cb)} + B^{cb}B_{ac} - \delta_b^a\sigma_{00} - 2n\sigma_0^2 - \sigma_b^a - \sigma^a\sigma_b = \alpha\delta_b^a \quad (0.2)$$

Contracting (0.2) by the indices (a, b) , we obtain

$$\alpha = \frac{1}{n}A_{ac}^{(ca)} + \frac{1}{n}B^{ca}B_{ac} - \sigma_{00} - 2n\sigma_0^2 - \frac{1}{n}(\sigma_a^a + \sigma^a\sigma_a) \quad .$$

Moreover, we have

$$-2n(\sigma_{00} + \sigma_0^2) - 2B_{hc}B^{ch} - 2(\sigma_c^c + \sigma^c\sigma_c) + 4\sigma^{[c}\delta_c^{h]}\sigma_h = \alpha + \beta \quad (0.3)$$

Symmtrizing and antisymmtrizing (0.3) by the indices (c, h) , we conclude

$$\beta = -\frac{1}{n}A_{ac}^{(ca)} - \frac{1}{n}B^{ca}B_{ac} - (2n-1)\sigma_{00} + (\frac{1}{n}-2)(\sigma_a^a + \sigma^a\sigma_a) \quad .$$

Now, if M is of constant curvature, then by the Theorem 0.1, directly we get that M is an Einstein manifold with a cosmological constant α . \square

Theorem 0.4 The Riemannian curvature tensor of \mathcal{LCA}_f -manifold M has the first special property, if M has the constant curvature k .

Theorem 0.5 The Riemannian curvature tensor of \mathcal{LCA}_f -manifold M has the second special property, if M has the constant curvature $k = 0$.

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